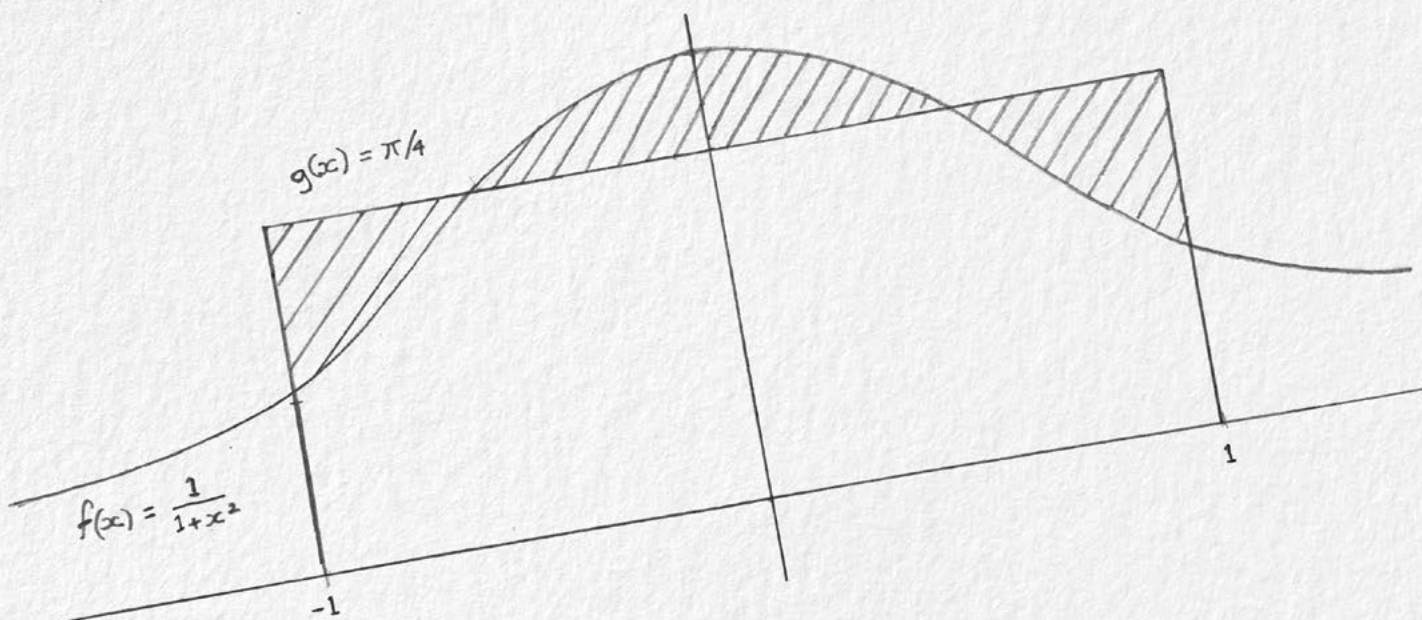


AS LEVEL
Specification

FURTHER MATHEMATICS B (MEI)

H635
For first assessment in 2018

Version 1.3 (September 2019)



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resources.feedback@ocr.org.uk

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1 Why choose an OCR AS Level in Further Mathematics B (MEI)?

1

1a. Why choose an OCR qualification?

Choose OCR and you've got the reassurance that you're working with one of the UK's leading exam boards. Our new AS Level in Further Mathematics B (MEI) course has been developed in consultation with teachers, employers and Higher Education to provide learners with a qualification that's relevant to them and meets their needs.

We're part of the Cambridge Assessment Group, Europe's largest assessment agency and a department of the University of Cambridge. Cambridge Assessment plays a leading role in developing and delivering assessments throughout the world, operating in over 150 countries.

We work with a range of education providers, including schools, colleges, workplaces and other institutions in both the public and private sectors. Over 13,000 centres choose our A Levels, GCSEs and vocational qualifications including Cambridge Nationals and Cambridge Technicals.

Our Specifications

We believe in developing specifications that help you bring the subject to life and inspire your learners to achieve more.

We've created teacher-friendly specifications based on extensive research and engagement with the teaching community. They're designed to be straightforward and accessible so that you can tailor the delivery of the course to suit your needs. We aim to encourage students to become responsible for their own learning, confident in discussing ideas, innovative and engaged.

We provide a range of support services designed to help you at every stage, from preparation through to the delivery of our specifications. This includes:

- A wide range of high-qsces including:
 - Delivery Guides
 - Transition Guides
 - Topic Exploration Packs
 - Lesson Elements
 - ...and much more.
- Access to Subject Advisors to support you through the transition and throughout the lifetime of the specification.
- CPD/Training for teachers including events to introduce the qualifications and prepare you for first teaching.
- Active Results – our free results analysis service to help you review the performance of individual learners or whole schools.
- ExamBuilder – our new, free online past papers service that enables you to build your own test papers from past OCR exam questions can be found at www.ocr.org.uk/exambuilder/.

All AS Level qualifications offered by OCR are accredited by Ofqual, the Regulator for qualifications offered in England. The accreditation number for OCR AS Level in Further Mathematics B (MEI) is QN603/1390/0.

1b. Why choose an OCR AS Level in Further Mathematics B (MEI)?

OCR AS Level in Further Mathematics B (MEI) has been developed by Mathematics in Education and Industry (MEI) and is assessed by OCR. This is a well-established partnership which provides a firm foundation for curriculum and qualification development.

MEI is a long-established, independent curriculum development body; in developing this specification,

MEI has consulted with teachers and representatives from Higher Education to decide how best to meet the long-term needs of learners.

MEI provides advice and CPD relating to all the curriculum and teaching aspects of the course. It also provides teaching resources, which for this specification can be found on the website (www.mei.org.uk).

Aims and learning outcomes

OCR AS Level in Further Mathematics B (MEI) will encourage learners to:

- understand mathematics and mathematical processes in ways that promote confidence, foster enjoyment and provide a strong foundation for progress to further study
- extend their range of mathematical skills and techniques
- understand coherence and progression in mathematics and how different areas of mathematics are connected
- apply mathematics in other fields of study and be aware of the relevance of mathematics to the world of work and to situations in society in general
- use their mathematical knowledge to make logical and reasoned decisions in solving problems both within pure mathematics and in a variety of contexts, and communicate the mathematical rationale for these decisions clearly
- reason logically and recognise incorrect reasoning
- generalise mathematically
- construct mathematical proofs
- use their mathematical skills and techniques to solve challenging problems which require them to decide on the solution strategy
- recognise when mathematics can be used to analyse and solve a problem in context
- represent situations mathematically and understand the relationship between problems in context and mathematical models that may be applied to solve them
- draw diagrams and sketch graphs to help explore mathematical situations and interpret solutions
- make deductions and inferences and draw conclusions by using mathematical reasoning
- interpret solutions and communicate their interpretation effectively in the context of the problem
- read and comprehend mathematical arguments, including justifications of methods and formulae, and communicate their understanding
- read and comprehend articles concerning applications of mathematics and communicate their understanding
- use technology such as calculators and computers effectively, and recognise when such use may be inappropriate
- take increasing responsibility for their own learning and the evaluation of their own mathematical development.

OCR AS Level in Further Mathematics B (MEI) is designed for learners with an enthusiasm for mathematics, many of whom will go on to degrees in mathematics, engineering, the sciences and economics, or any subject where mathematics is developed further than in A Level Mathematics.

AS and A Level Further Mathematics build from GCSE, AS and A Level Mathematics. As well as building on algebra and calculus introduced in A Level Mathematics, the AS Level Further Mathematics core content introduces complex numbers and matrices,

fundamental mathematical ideas with wide applications in mathematics, engineering, physical sciences and computing. The non-core content includes different options that can enable learners to specialise in areas of mathematics that are particularly relevant to their interests and future aspirations. AS Level Further Mathematics prepares learners for further study and employment in highly mathematical disciplines that require knowledge and understanding of sophisticated mathematical ideas and techniques.

1c. What are the key features of this specification?

OCR AS Level in Further Mathematics B (MEI) has been designed to help learners to fulfil their potential in mathematics and to support teachers in enabling them to do this. The specification:

- encourages learners to develop a deep understanding of mathematics and an ability to use it in a variety of contexts
- allows a choice of two options from six to enable teachers to create the most appropriate course for their students
- encourages learners to use appropriate technology to deepen their mathematical understanding and extend the range of problems which they are able to solve

- is assessed in a way which is designed to enable all learners to show what they are able to do
- is clearly laid out with detailed guidance regarding what learners need to be able to do
- is resourced and supported by MEI in line with the aims and learning outcomes of the qualification.

This specification is co-teachable with AS Level Mathematics B (MEI) and with the first year of A Level Further Mathematics B (MEI). Alternatively it can be taught alongside the second year of A Level Mathematics B (MEI); two of the optional units are designed with this model in mind.

1d. How do I find out more information?

If you are already using OCR specifications you can contact us at: www.ocr.org.uk

If you are not already a registered OCR centre then you can find out more information on the benefits of becoming one at: www.ocr.org.uk

If you are not yet an approved centre and would like to become one go to: www.ocr.org.uk

Want to find out more?

Get in touch with one of OCR's Subject Advisors:

Email: maths@ocr.org.uk

Customer Contact Centre: 01223 553998

Teacher support: www.ocr.org.uk

Advice and support is also available from MEI; contact details can be found on www.mei.org.uk

2 The specification overview

2a. OCR AS Level in Further Mathematics B (MEI) (H635)

OCR's AS Level in Further Mathematics B (MEI) is a linear qualification in which all papers must be taken in the same examination series.

Learners must take the mandatory paper Core Pure (Y410) and then any **two** from the six optional papers to be awarded OCR's AS Level in Further Mathematics B (MEI).

Learners may take more than the two optional papers to increase the breadth of their course. For details of how their grade will be awarded, see Section 3g.

Content Overview	Assessment Overview	
<p>Content is in two areas:</p> <ul style="list-style-type: none"> • Core Pure content • Options (any two of the following six): <ul style="list-style-type: none"> Y411 Mechanics a Y412 Statistics a Y413 Modelling with Algorithms Y414 Numerical Methods Y415 Mechanics b¹ Y416 Statistics b¹ <p>The overarching Themes are assessed in all papers. See Section 2b.</p> <p>¹These options are designed to be taught alongside the non-AS content of A Level Mathematics.</p>	<p>Mandatory paper:</p> <p>Core Pure (Y410)</p> <p>60 marks</p> <p>1 hour 15 minutes</p> <p>Written paper</p>	<p>33⅓% of total AS level</p>
	<p>Optional paper:</p> <p>60 marks</p> <p>1 hour 15 minutes</p> <p>Written paper</p>	<p>33⅓% of total AS level</p>
	<p>Optional paper:</p> <p>60 marks</p> <p>1 hour 15 minutes</p> <p>Written paper</p>	<p>33⅓% of total AS level</p>

2b. Content of AS Level in Further Mathematics B (MEI) (H635)

This AS Level qualification builds on the skills, knowledge and understanding set out in the whole GCSE subject content for mathematics and the subject content for AS Level Mathematics. Problem solving, proof and mathematical modelling will be assessed in Further Mathematics in the context of the wider knowledge which students taking AS Level Further Mathematics will have studied.

The content is made up of the mandatory Core Pure (Y410) plus any **two** from the optional content:

- Mechanics a (Y411)
- Statistics a (Y412)
- Modelling with Algorithms (Y413)
- Numerical Methods (Y414)
- Mechanics b (Y415)
- Statistics b (Y416)

The content of Mechanics b (Y415) also builds on some of the skills, knowledge and understanding set out in the content of Mechanics a (Y411). It is permitted that learners enter for Mechanics b (Y415) without entering for Mechanics a (Y411), but this content dependency should be noted. Mechanics b (Y415) also builds on some of the content of A Level Mathematics not in AS Mathematics. Further details may be found at the beginning of section 2h.

The content of Statistics b (Y416) also builds on some of the skills, knowledge and understanding set out in the content of Statistics a (Y412). It is permitted that learners enter for Statistics b (Y416) without entering for Statistics a (Y412), but this content dependency should be noted. Statistics b (Y416) also builds on some of the content of A Level Mathematics not in AS Mathematics. Further details may be found at the beginning of section 2i.

The overarching themes should be applied along with associated mathematical thinking and understanding, across every permissible combination of papers in this specification.

The applied optional papers (Mechanics a, Statistics a, Modelling with Algorithms, Mechanics b, Statistics b) should be regarded as applications of pure maths as well as ways of thinking about the world in their own right. The Numerical Methods paper extends the range of non-analytic techniques for solving a wider class of problems from within pure maths. In all of these cases, appropriate links should be made with the content of AS Level Mathematics and the content of the Core Pure paper in this AS Level Further Mathematics B (MEI).

Formulae and statistical tables

Some formulae will be available to learners in the examination, in a separate formulae booklet. A list of these formulae can be found in Section 5d. This list also contains the statistical tables which will be available to learners in the examination.

Use of calculators

Learners are permitted to use a scientific or graphical calculator for all papers. Calculators are subject to the rules in the document *Instructions for Conducting Examinations*, published annually by JCQ (www.jcq.org.uk).

It is expected that calculators available in the assessment will include the following features:

- An iterative function such as an ANS key.
- The ability to perform calculations, including inversion, with matrices up to at least order 3×3 .
- The ability to compute summary statistics and access probabilities from the binomial, Poisson and Normal distributions.

Calculators with spreadsheets and graph-drawing functionality are permitted in all examination papers, but this functionality is not required.

Generally, permitted calculators may be used for any function they can perform.

When using calculators, learners should bear in mind the following:

1. Learners are advised to write down explicitly any expressions, including integrals, that they use the calculator to evaluate.
2. Learners are advised to write down the values of any parameters and variables that they input into the calculator. Learners are not expected to write down data transferred from question paper to calculator.
3. Correct mathematical notation (rather than “calculator notation”) should be used; incorrect notation may result in loss of marks.

In the Numerical Methods optional paper, learners are expected to show evidence of working through methods rather than just writing down solutions provided by equation solvers or numerical differential or integration functions on calculators.

Example for Numerical Methods:

Show that the equation $x^5 - 5x + 1 = 0$ has a root in the interval $[0, 1]$.

Using a calculator equation solver to find the three real roots 1.44, 0.2 and -1.54 and stating that one of them lies in the required interval would not be awarded marks. An acceptable method would be to evaluate $x^5 - 5x + 1$ at 0 and 1 and explain that the change of sign indicates that there is a root in the interval.

These are not restrictions on a learner’s use of a calculator when tackling the question, e.g. for checking an answer or evaluating a function at a given point, but it is a restriction on what will be accepted as evidence of a complete method.

Use of technology

It is expected that learners will have used appropriate technology including mathematical graphing tools and spreadsheets when studying AS Level Further Mathematics B (MEI). Several options have their own requirements for generic software which learners will have used. The content sections give more detail, including what is expected in the examination. In general, learners are not expected to be familiar with particular software, nor will they be expected to use the syntax associated with particular software but examination questions may include output from software which learners will need to complete or interpret. However, the Numerical Methods optional paper will also assess learners’ ability to write some spreadsheet formulae.

Simplifying expressions

It is expected that learners will simplify algebraic and numerical expressions when giving their final

answers, even if the examination question does not explicitly ask them to do so:

- $80\frac{\sqrt{3}}{2}$ should be written as $40\sqrt{3}$.
- $\frac{1}{3-\sqrt{2}}$ should be written as $\frac{3+\sqrt{2}}{7}$.
- $\frac{1}{2}(1+2x)^{-\frac{1}{2}} \times 2$ should be written as either $(1+2x)^{-\frac{1}{2}}$ or $\frac{1}{\sqrt{1+2x}}$.
- $\ln 2 + \ln 3 - \ln 1$ should be written as $\ln 6$.
- The equation of a straight line should be given in the form $y = mx + c$ or $ax + by = c$ unless otherwise stated.

The meanings of some instructions used in examination questions

In general, learners should show sufficient detail of their working and reasoning to indicate that a correct method is being used. The following command words are used to indicate when more, or less, specific detail is required.

Exact

An exact answer is one where numbers are not given in rounded form. The answer will often contain an irrational number such as $\sqrt{3}$, e or π and these numbers should be given in that form when an exact answer is required. The use of the word 'exact' also tells learners that rigorous (exact) working is expected in the answer to the question.

e.g. Find the exact solution of $\ln x = 2$.

The correct answer is e^2 and not 7.389 056.

e.g. Find the exact solution of $3x = 2$.

The correct answer is $x = \frac{2}{3}$ or $x = 0.6$, not $x = 0.67$ or similar.

Prove

Learners are given a statement and must provide a formal mathematical argument which demonstrates its validity. A formal proof requires a high level of mathematical detail, with candidates clearly defining variables, correct algebraic manipulation and a concise conclusion.

Show that

Learners are given a result and have to get to the given result from the starting information. Because they are given the result, the explanation has to be sufficiently detailed to cover every step of their working, e.g. Show that the curve $y = x \ln x$ has a stationary point $\left(\frac{1}{e}, -\frac{1}{e}\right)$.

Determine

This command word indicates that justification should be given for any results found, including working where appropriate.

Verify

A clear substitution of the given value to justify the statement is required.

Find, Solve, Calculate

These command words indicate, while working may be necessary to answer the question, no justification is required. A solution could be obtained from the efficient use of a calculator, either graphically or using a numerical method.

Give, State, Write down

These command words indicate that neither working nor justification is required.

In this question you must show detailed reasoning.

When a question includes this instruction learners must give a solution which leads to a conclusion showing a detailed and complete analytical method. Their solution should contain sufficient detail to allow the line of their argument to be followed. This is not a restriction on a learner's use of a calculator when tackling the question, e.g. for checking an answer or evaluating a function at a given point, but it is a restriction on what will be accepted as evidence of a complete method.

In these examples variations in the structure of the answers are possible and different intermediate steps may be given.

Example 1:

Express $-4 + 2i$ in modulus-argument form.

The answer is $\sqrt{20}(\cos 2.68 + i \sin 2.68)$,

but the learner *must* include the steps

$$|-4 + 2i| = \sqrt{16 + 4} = \sqrt{20},$$

$\arg(-4 + 2i) = \pi - \tan^{-1}(0.5) = 2.68$. Using a calculator in complex mode to convert to modulus-argument form would not result in a complete analytical method.

Example 2:

Solve the equation $2x^3 - 11x^2 + 22x - 15 = 0$.

The answer is $1.5, 2 \pm i$, but the learner *must* include steps to find a real root or corresponding factor, find the factor $(2x-3)$ and factorise the cubic then solve the quadratic. Just writing down the three roots by using the cubic equation solver on a calculator would not be awarded any marks.

Hence

When a question uses the word ‘hence’, it is an indication that the next step should be based on what has gone before. The intention is that learners should start from the indicated statement.

e.g. You are given that $f(x) = 2x^3 - x^2 - 7x + 6$. Show that $(x-1)$ is a factor of $f(x)$. Hence find the three factors of $f(x)$.

Hence or otherwise is used when there are multiple ways of answering a given question. Learners starting from the indicated statement may well gain some information about the solution from doing so, and may already be some way towards the answer. The command phrase is used to direct learners towards using a particular piece of information to start from or to a particular method. It also indicates to learners that valid alternative methods exist which will be given full credit, but that they may be more time-consuming or complex.

e.g. Show that $(\cos x + \sin x)^2 = 1 + \sin 2x$ for all x . Hence, or otherwise, find the derivative of $(\cos x + \sin x)^2$.

You may use the result

When this phrase is used it indicates a given result that learners would not always be expected to know, but which may be useful in answering the question. The phrase should be taken as permissive; use of the given result is not required.

Plot

Learners should mark points accurately on graph paper provided in the Printed Answer Booklet. They will either have been given the points or have had to calculate them. They may also need to join them with a curve or a straight line, or draw a line of best fit through them.

e.g. Plot this additional point on the scatter diagram.

Sketch (a graph)

Learners should draw a diagram, not necessarily to scale, showing the main features of a curve. These are likely to include at least some of the following:

- Turning points
- Asymptotes
- Intersection with the y -axis
- Intersection with the x -axis
- Behaviour for large x (+ or -)

Any other important features should also be shown.

e.g. Sketch the curve with equation $y = \frac{1}{(x-1)}$

Draw

Learners should draw to an accuracy appropriate to the problem. They are being asked to make a sensible judgement about the level of accuracy which is appropriate.

e.g. Draw a diagram showing the forces acting on the particle.

e.g. Draw a line of best fit for the data.

Other command words

Other command words, for example “explain”, will have their ordinary English meaning.

Overarching Themes

These must be applied, along with associated mathematical thinking and understanding, across the whole of the detailed content set out below. These

statements, similar to those in A Level Mathematics, are intended to direct the teaching and learning of AS Level Further Mathematics, and they will be reflected in assessment tasks.

OT1 Mathematical argument, language and proof

	Knowledge/Skill
OT1.1	Construct and present mathematical arguments through appropriate use of diagrams; sketching graphs; logical deduction; precise statements involving correct use of symbols and connecting language, including: constant, coefficient, expression, equation, function, identity, index, term, variable
OT1.2	Understand and use mathematical language and syntax as set out in the glossary
OT1.3	Understand and use language and symbols associated with set theory, as set out in the glossary
OT1.4	Not Applicable to AS Level Further Mathematics
OT1.5	Comprehend and critique mathematical arguments, proofs and justifications of methods and formulae, including those relating to applications of mathematics

OT2 Mathematical problem solving

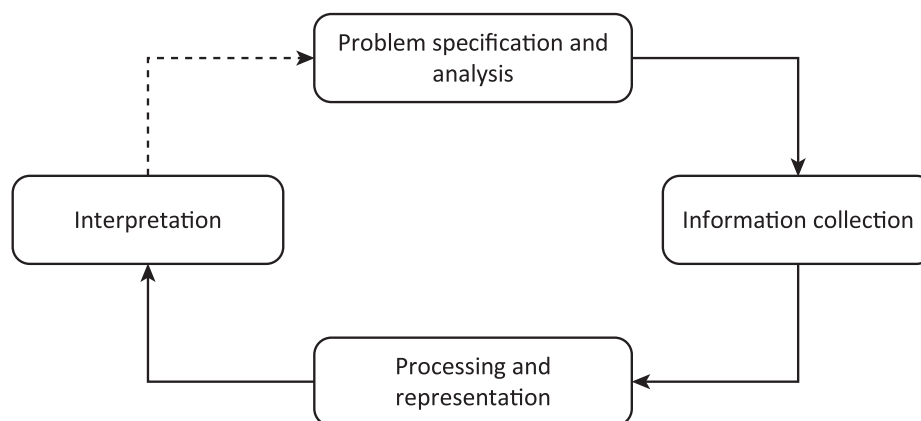
	Knowledge/Skill
OT2.1	Recognise the underlying mathematical structure in a situation and simplify and abstract appropriately to enable problems to be solved
OT2.2	Construct extended arguments to solve problems presented in an unstructured form, including problems in context
OT2.3	Interpret and communicate solutions in the context of the original problem
OT2.4	Not Applicable to AS Level Further Mathematics
OT2.5	Not Applicable to AS Level Further Mathematics
OT2.6	Understand the concept of a mathematical problem solving cycle, including specifying the problem, collecting information, processing and representing information and interpreting results, which may identify the need to repeat the cycle
OT2.7	Understand, interpret and extract information from diagrams and construct mathematical diagrams to solve problems

OT3 Mathematical modelling

	Knowledge/Skill
OT3.1	Translate a situation in context into a mathematical model, making simplifying assumptions
OT3.2	Use a mathematical model with suitable inputs to engage with and explore situations (for a given model or a model constructed or selected by the student)
OT3.3	Interpret the outputs of a mathematical model in the context of the original situation (for a given model or a model constructed or selected by the student)
OT3.4	Understand that a mathematical model can be refined by considering its outputs and simplifying assumptions; evaluate whether the model is appropriate
OT3.5	Understand and use modelling assumptions

Mathematical Problem Solving Cycle

Mathematical problem solving is a core part of mathematics. The problem solving cycle gives a general strategy for dealing with problems which can be solved using mathematical methods; it can be used for problems within mathematical contexts and for problems in real-world contexts.



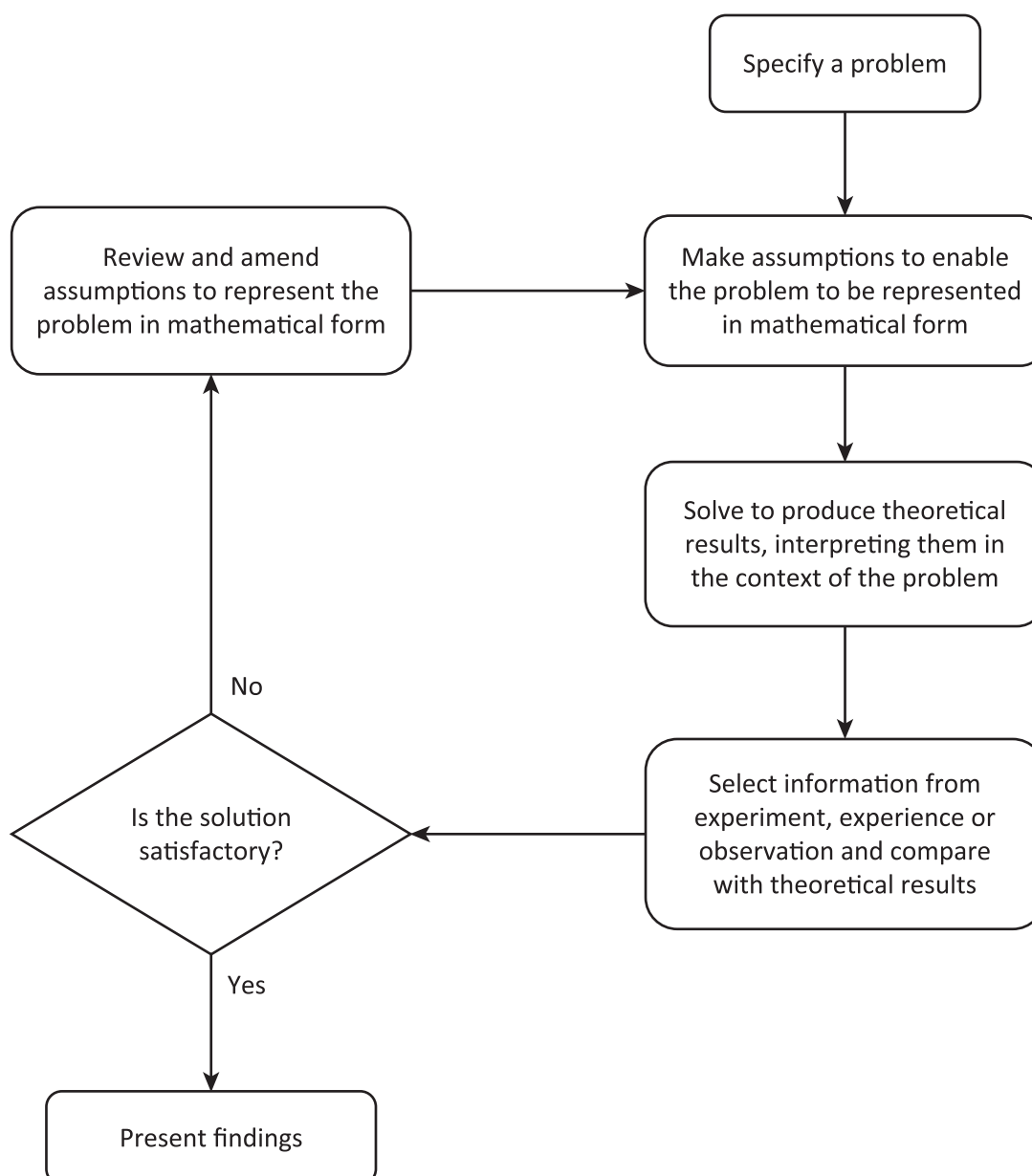
Process	Description
Problem specification and analysis	<p>The problem to be addressed needs to be formulated in a way which allows mathematical methods to be used. It then needs to be analysed so that a plan can be made as to how to go about it. The plan will almost always involve the collection of information in some form. The information may already be available (e.g. online) or it may be necessary to carry out some form of experimental or investigational work to gather it.</p> <p>In some cases the plan will involve considering simple cases with a view to generalising from them. In others, physical experiments may be needed. In statistics, decisions need to be made at this early stage about what data will be relevant and how they will be collected.</p> <p>The analysis may involve considering whether there is an appropriate standard model to use (e.g. the Normal distribution or the particle model) or whether the problem is similar to one which has been solved before.</p> <p>At the completion of the problem solving cycle, there needs to be consideration of whether the original problem has been solved in a satisfactory way or whether it is necessary to repeat the problem solving cycle in order to gain a better solution. For example, the solution might not be accurate enough or only apply in some cases.</p>
Information collection	<p>This stage involves getting the necessary inputs for the mathematical processing that will take place at the next stage. This may involve deciding which are the important variables, finding key measurements or collecting data.</p>
Processing and representation	<p>This stage involves using suitable mathematical techniques, such as calculations, graphs or diagrams, in order to make sense of the information collected in the previous stage. This stage ends with a provisional solution to the problem.</p>
Interpretation	<p>This stage of the process involves reporting the solution to the problem in a way which relates to the original situation. Communication should be in clear, plain English which can be understood by someone who has an interest in the original problem but is not an expert in mathematics. This should lead into reflection on the solution to consider whether it is satisfactory or further work is needed.</p>

The Modelling Cycle

The examinations will assume that learners have used the full modelling cycle during the course.

Mathematics can be applied to a wide variety of **problems** arising from real situations but real life is complicated, and can be unpredictable, so some **assumptions** need to be made to simplify the situation and allow mathematics to be used. Once answers have been obtained, we need to **compare with experience** to make sure that the answers are useful.

For example, the government might want to know the effects of different possible regulations on catching fish so that they can put the right rules in place to safeguard fish stocks for the future. To model the effects of catching fish, they might **assume** that the population growth rate depends on the number of fish of breeding age. They would **evaluate** these assumptions by checking whether they fit in with **past data** and then model the effects of removing fish from the population in accordance with the proposed rules. **New data** about fish populations after new rules are put in place would be **reviewed** to check whether the model is making reasonable predictions.



Learning outcomes

Learning outcomes are designed to help users by clarifying the requirements, but the following points need to be noted:

- Content that is covered by a Learning outcomes with a reference code may be tested in an examination question without further guidance being given.
- Learning outcomes marked with an asterisk * are assumed knowledge and will not form the focus of any examination questions. These outcomes are included for clarity and completeness.
- Many examination questions will require learners to use two or more learning outcomes at the same time without further guidance being given. Learners are expected to be able to make links between different areas of mathematics.
- Learners are expected to be able to use their knowledge to reason mathematically and solve problems both within mathematics and in context. Content that is covered by any learning outcomes may be required in problem solving, modelling and reasoning tasks even if that is not explicitly stated in the learning outcomes.
- Learning outcomes have an implied prefix: 'A learner should ...'
- Each reference code for a learning outcomes is unique. For example, in the code MG1, M refers to Mechanics, G refers to 'centre of mass' (see below) and 1 means that it is the first such competence statement in the list.
- The letters used in assigning reference codes to learning outcomes are shown below:

a	algebra
b	bivariate data
c	calculus
d	dynamics
e	equations
f	functions
g	geometry, graphs
h	Hooke's law
i	impulse and momentum
j	complex numbers
k	kinematics
l	
m	matrices
n	Newton's laws
o	
p	mathematical processes (modelling, proof, etc)
q	dimensions (quantities)
r	rotation
s	sequences and series
t	trigonometry
u	probability (uncertainty)
v	vectors
w	work, energy and power
x	experimental design
y	projectiles
z	

A	Algorithms
B	
C	Curves, Curve sketching
D	Data presentation & interpretation
E	Exponentials and logarithms
F	Forces
G	Centre of mass
H	Hypothesis testing
I	Inference
J	
K	
L	Linear programming
M	
N	Networks
O	
P	Polar coordinates
Q	Technology
R	Random variables
S	Sets and logic
T	Number theory
U	Errors (uncertainty)
V	
W	
X	
Y	
Z	Simulation

Notes, notation and exclusions

The notes, notation and exclusions columns in the specification are intended to assist teachers and learners.

- The notes column provides examples and further detail for some learning outcomes. All exemplars contained in the specification are for illustration only and do not constitute an exhaustive list.
- The notation column shows the notation and terminology that learners are expected to know, understand and be able to use.
- The exclusions column lists content which will **not** be tested, for the avoidance of doubt when interpreting learning outcomes.

2

2c. Content of Core Pure (Y410) – mandatory paper

Description	In this mandatory paper some pure topics from AS Level Mathematics are studied in greater depth, while some new topics are introduced. Algebraic work with series is extended. The powerful technique of proof by induction is used in various contexts. Complex numbers are introduced, including their geometrical representation. Matrices are used to solve systems of equations and to explore transformations. Scalar products of vectors are applied to problems involving planes.
Assumed knowledge	Learners are expected to know the content of AS Level Mathematics.
Assessment	One examination paper
Length of paper	1 hour 15 minutes
Number of marks	60
Percentage of qualification	This mandatory paper counts for 33⅓% of the qualification OCR AS Level Further Mathematics B (MEI) (H635).
Use of calculator and other technology	See Section 2b for details about the use of calculators.
Overarching Themes	The Overarching Themes (see Section 2b) apply. Some questions may be set in a real-world context and require some modelling.
Relationship with other papers	The content is the same as one third of the Core Pure (Y420) content in the qualification OCR A Level Further Mathematics B (MEI) (H645).
Other notes	

**Core Pure (Y410)
Contents**

Proof	Proof by induction is introduced for formulae for simple sequences, sums of simple series and powers of matrices.
Complex numbers	Complex numbers and their basic arithmetic are introduced, including in modulus-argument form. They are used to solve polynomial equations with real coefficients and to define loci on the Argand diagram.
Matrices and transformations	Matrix arithmetic is introduced and applied to linear transformations in 2-D, and some in 3-D. Inverses of matrices (which may be found using a calculator in the 3×3 case) are used to solve matrix equations and related to inverse transformations.
Vectors and 3-D space	Scalar products are introduced, and used to form the equation of a plane. How planes intersect in 3-D space is considered, and matrices are used to find the point(s) of intersection.
Algebra	Relationships between roots of and coefficients of polynomials are explored.
Series	Standard formulae and the method of differences are used to calculate the sum of the given series.

Specification	Ref.	Learning outcomes	Notes	Notation	Exclusions
CORE PURE: PROOF (a)					
Proof	*	Be able to prove mathematical results by deduction and exhaustion, and disprove false conjectures by counter-example.	Includes proofs of results used in this specification, where appropriate.		
Induction	Pp4	Be able to construct and present a proof using mathematical induction for given results for a formula for the n th term of a simple sequence, the sum of a simple series or the n th power of a matrix.	The result to be proved will be given. E.g. for the sequence given by $u_1 = 0$, $u_{n+1} = u_n + 2n$ prove that $u_n = n^2 - n$.	$u_n, \sum_{r=1}^n r^2$	
CORE PURE: COMPLEX NUMBERS (a)					
Language of complex numbers	Pj1	Understand the language of complex numbers.	Real part, imaginary part, complex conjugate, modulus, argument, real axis, imaginary axis.	$z = x + yi$ $z^* = x - yi$ $\text{Re}(z) = x, \text{Im}(z) = y$	
Complex numbers and polynomial equations with real coefficients	j2	Be able to solve any quadratic equation with real coefficients.		$i^2 = -1$	
	j3	Know that the complex roots of polynomial equations with real coefficients occur in conjugate pairs. Be able to solve cubic or quartic equations with real coefficients.	Use of the factor theorem once a real root has been determined. Sufficient information will be given to deduce at least one complex root or quadratic factor for quartics.		Equations with degree > 4 .
Arithmetic of complex numbers	j4	Be able to add, subtract, multiply and divide complex numbers given in the form $x + yi$, x and y real.	Division using complex conjugates.		
	j5	Understand that a complex number is zero if and only if both the real and imaginary parts are zero.			

Specification	Ref.	Learning outcomes	Notes	Notation	Exclusions
CORE PURE: COMPLEX NUMBERS (a)					
Modulus-argument form	j6	Be able to use radians in the context of complex numbers.	Use exact values of trigonometric functions for multiples of $\frac{\pi}{4}$ and $\frac{\pi}{6}$.		
	j7	Be able to represent a complex number in modulus-argument form. Be able to convert between the forms $z = x + yi$ and $z = r(\cos \theta + i \sin \theta)$ where r is the modulus and θ is the argument of the complex number.	$zz^* = z ^2$	$ z $ is the modulus of z . $\arg(z)$ for principal argument, where $-\pi < \arg(z) \leq \pi$. Radian measure.	
	j8	Be able to multiply and divide complex numbers in modulus-argument form.	$z_1 z_2 = r_1 r_2 [\cos(\theta_1 + \theta_2) + i \sin(\theta_1 + \theta_2)]$ $\frac{z_1}{z_2} = \frac{r_1}{r_2} [\cos(\theta_1 - \theta_2) + i \sin(\theta_1 - \theta_2)]$ The identities for $\sin(\theta \pm \phi)$ and $\cos(\theta \pm \phi)$ may be assumed in the derivation of these results.		
The Argand diagram	j9	Be able to represent and interpret complex numbers and their conjugates on an Argand diagram.			
	j10	Be able to represent the sum, difference, product and quotient of two complex numbers on an Argand diagram.			
	j11	Be able to represent and interpret sets of complex numbers as simple loci on an Argand diagram.	Circles of the form $ z - a = r$. Half lines of the form $\arg(z - a) = \theta$. Lines of the form $ z - a = z - b $. Regions defined by inequalities based on the above. E.g. $ z - a > r$. Intersections and unions of these.	For regions defined by inequalities learners must state clearly which regions are included and whether the boundaries are included. No particular shading convention is expected.	$ z - a = k z - b $ for $k \neq 1$.

Specification	Ref.	Learning outcomes	Notes	Notation	Exclusions
CORE PURE: MATRICES AND TRANSFORMATIONS (a)					
Matrix addition and multiplication	Pm1	Be able to add, subtract and multiply conformable matrices, and to multiply a matrix by a scalar.	With and without a calculator for matrices up to 3×3 .	$\mathbf{M} = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$	
	m2	Understand and use the zero and identity matrices, understand what is meant by equal matrices.		0 (zero) I (identity).	
	m3	Know that matrix multiplication is associative but not commutative.			
Linear transformations and their associated matrices	m4	Be able to find the matrix associated with a linear transformation and vice versa.	2-D transformations include the following. <ul style="list-style-type: none"> • Reflection in the x and y axes and in $y = \pm x$. • Rotation centre the origin through an angle θ (counter clockwise positive). • Enlargement centre the origin. • Stretch parallel to x or y axis. • Shear x or y axis fixed, shear factor¹. 3-D transformations will be confined to reflection in one of $x = 0, y = 0, z = 0$ or rotation of multiples of 90° about x, y or z axis ² . Learners should know that any linear transformation may be represented by a matrix.	Matrices will be shown in bold type, transformations in non-bold type. The image of the column vector \mathbf{r} under the transformation associated with matrix \mathbf{M} is \mathbf{Mr} .	
	¹ A shear may be defined by giving the fixed line and the image of a point. (The fixed line of a shear is a line of invariant points.) The shear factor is the distance moved by a point divided by its perpendicular distance from the fixed line. Learners should know this, but the shear factor should not be used to define a shear as there are different conventions about the sign of a shear factor. ² Positive angles counter clockwise when looking towards the origin from the positive side of the axis of rotation.				
	m5	Understand successive transformations in two dimensions and the connection with matrix multiplication.	Describe a transformation as a combination of two of those above.		More than 2 dimensions.
	*	Understand the language of vectors in two dimensions and three dimensions.	Scalar, vector, modulus, magnitude, direction, position vector, unit vector, cartesian components, equal vectors, parallel vectors.	$\mathbf{i}, \mathbf{j}, \mathbf{k}, \hat{\mathbf{r}}, \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix}$	

Specification	Ref.	Learning outcomes	Notes	Notation	Exclusions
CORE PURE: MATRICES AND TRANSFORMATIONS (a)					
Invariance	Pm6	Know the meaning of, and be able to find, invariant points and invariant lines for a linear transformation.			More than 2 dimensions.
Determinant of a matrix	m7	Be able to calculate the determinant of a 2×2 matrix and a 3×3 matrix. Know the meaning of the terms singular and non-singular as applied to matrices.	With a calculator for 3×3 matrices. A singular square matrix is non-invertible and therefore has determinant zero.	$\begin{vmatrix} a & b \\ c & d \end{vmatrix}$ or $\det \mathbf{M}$ or $ \mathbf{M} $.	
	m8	Know that the magnitude of the determinant of a 2×2 matrix gives the area scale factor of the associated transformation, and understand the significance of a zero determinant. Interpret the sign of a determinant in terms of orientation of the image.	E.g. Quadrilateral ABCD is labelled clockwise and transformed in 2-D; a negative determinant for the transformation matrix means that the labelling on the image $A'B'C'D'$ is anticlockwise.		Proof.
	m9	Know that the magnitude of the determinant of a 3×3 matrix gives the volume scale factor of the associated transformation, and understand the significance of a zero determinant. Interpret the sign of a determinant in terms of orientation of the image.	The sign of the determinant determines whether the associated transformation preserves or reverses orientation ('handedness'). E.g. If a triangle ABC is labelled clockwise when seen from point S, then for a negative determinant, the triangle $A'B'C'$ is labelled anti-clockwise when seen from S' .		Proof.
	m10	Know that $\det(\mathbf{MN}) = \det \mathbf{M} \times \det \mathbf{N}$ and the corresponding result for scale factors of transformations.	Scale factors in 2-D only.		Algebraic proof.
Inverses of square matrices	m11	Understand what is meant by an inverse matrix.	Square matrices of any order.	\mathbf{M}^{-1}	
	m12	Be able to calculate the inverse of a non-singular 2×2 matrix or 3×3 matrix.	With a calculator for 3×3 matrices. $\det(\mathbf{A}^{-1}) = \frac{1}{\det \mathbf{A}}$		
	m13	Be able to use the inverse of a non-singular 2×2 or 3×3 matrix. Relate the inverse matrix to the corresponding inverse transformation.	E.g. to solve a matrix equation and interpret in terms of transformations: find the pre-image of a transformation.		
	m14	Understand and use the product rule for inverse matrices.	$(\mathbf{AB})^{-1} = \mathbf{B}^{-1} \mathbf{A}^{-1}$		

Specification	Ref.	Learning outcomes	Notes	Notation	Exclusions
CORE PURE: VECTORS AND 3-D SPACE (a)					
Scalar products and the equations of planes	Pv1	Know how to calculate the scalar product of two vectors, and be able to use the two forms of the scalar product to find the angle between two vectors.	Including test for perpendicular vectors.	$\mathbf{a} \cdot \mathbf{b}$ $= a_1 b_1 + a_2 b_2 + a_3 b_3$ $= \mathbf{a} \mathbf{b} \cos \theta$	Proof of equivalence of two forms in general case.
	v2	Be able to form and use the vector and cartesian equations of a plane. Convert between vector and cartesian forms for the equation of a plane.	Plane: $(\mathbf{r} - \mathbf{a}) \cdot \mathbf{n} = 0$ $n_1 x + n_2 y + n_3 z + d = 0$ where $d = -\mathbf{a} \cdot \mathbf{n}$.		The form $\mathbf{r} = \mathbf{a} + \lambda \mathbf{b} + \mu \mathbf{c}$.
	v3	Know that a vector which is perpendicular to a plane is perpendicular to any vector in the plane.	If a vector is perpendicular to two non-parallel vectors in a plane, it is perpendicular to the plane.		
Intersection of planes	v4	Know the different ways in which three distinct planes can be arranged in 3-D space.	If two planes are parallel the third can be parallel or cut the other two in parallel lines; if no pair is parallel the planes can intersect in a point, form a sheaf or form a prismatic intersection.	A sheaf is where three planes share a common line. A prismatic intersection is where each pair of planes meets in a line; the three lines are parallel.	
	v5	Be able to solve three linear simultaneous equations in three variables by use of the inverse of the corresponding matrix. Interpret the solution or failure of solution geometrically in terms of the arrangement of three planes. Be able to find the intersection of three planes when they meet in a point.	Inverse obtained using a calculator. If the corresponding matrix is singular, learners should know the possible arrangements of the planes; they will be given extra information or guidance if required to distinguish between these arrangements.		Finding equation of lines of intersection of two planes.
	v6	Know that the angle between two planes can be found by considering the angle between their normals.	The angle between two non-perpendicular planes is the acute angle between them.		

Specification	Ref.	Learning outcomes	Notes	Notation	Exclusions
CORE PURE: ALGEBRA (a)					
Relations between the roots and coefficients of polynomial equations	Pa1	Understand and use the relationships between the roots and coefficients of quadratic, cubic and quartic equations.		Roots $\alpha, \beta, \gamma, \delta$.	Equations of degree ≥ 5 .
	a2	Be able to form a new equation whose roots are related to the roots of a given equation by a linear transformation.	For a cubic or quartic equation.		Non-linear transformations of roots.
CORE PURE: SERIES (a)					
Summation of series	Ps1	Be able to use standard formulae for $\sum r$, $\sum r^2$ and $\sum r^3$ and the method of differences to sum series.	Formulae for $\sum r^2$ and $\sum r^3$ will be given but proof could be required. E.g. by induction.	$\sum_{r=1}^n r^2$	

2d. Content of Mechanics a (Y411) - option

Description	In this option, basic principles of forces and their moments, work and energy, impulse and momentum and centres of mass are used to model various situations, including: rigid bodies in equilibrium; particles moving under gravity or on a surface; bodies colliding with direct impact.
Assumed knowledge	Learners are expected to know the content of AS Level Mathematics and the Core Pure mandatory paper (Y410). Some concepts overlap with A Level Mathematics content not in AS Level Mathematics; these are labelled †.
Assessment	One examination paper
Length of paper	1 hour 15 minutes
Number of marks	60
Sections	The examination paper will not have sections.
Percentage of qualification	This optional paper counts for 33⅓% of the qualification OCR AS Level Further Mathematics B (MEI) (H635).
Use of calculator and other technology	See Section 2b for details about the use of calculators.
Overarching Themes	The Overarching Themes (see Section 2b) apply. Mechanics is about modelling the real world, so knowledge of the real world appropriate to a learner on this course will be assumed. Examination questions may include, for example, asking learners to suggest an explanation for a discrepancy between the results of a class experiment and the theoretical answer they have obtained; learners are expected to comment sensibly about the modelling assumptions in their answer.
Relationship with other papers	This option comprises the same content as Mechanics Minor (Y431) and the same content as the sections labelled (a) in Mechanics Major (Y421) in the qualification OCR A Level Further Mathematics B (MEI) (H645).
Other notes	The acceleration due to gravity is denoted by $g \text{ ms}^{-2}$. Unless otherwise instructed, when a numerical value is needed, learners should use $g = 9.8$. When making calculations within a model, learners are advised to use exact numbers (e.g. fractions or surds) where possible. When interpreting solutions in a practical context, rounding to an appropriate degree of accuracy is expected. † refers to content which overlaps or depends on non-AS content from A Level Mathematics.

Mechanics a (Y411)
Contents

Dimensional analysis	The dimensions of quantities are analysed in terms of mass, length and time; this allows checking of results and prediction of suitable models in some cases.
Forces	Work on the vector treatment of forces and friction is extended to consider the equilibrium of a particle and of a rigid body.
Work, energy and power	Consideration of kinetic energy, gravitational potential energy and the work done by a force leading to situations which can be modelled using the work-energy principle or conservation of energy. Power is introduced.
Momentum and impulse	Conservation of linear momentum and Newton's experimental law are used to model situations involving direct impact collisions. Mechanical energy lost in a collision is calculated.
Centre of mass	The centre of mass of systems of particles and some given shapes are used in situations involving equilibrium of a rigid body.

Specification	Ref.	Learning outcomes	Notes	Notation	Exclusions
MECHANICS a: DIMENSIONAL ANALYSIS					
Dimensional consistency	Mq1	Be able to find the dimensions of a quantity in terms of M, L, T.	Know the dimensions of angle and frequency. Work out without further guidance the dimensions of density (mass per unit volume), pressure (force per unit area) and other quantities in this specification. Other kinds of density will be referred to as e.g. mass per unit area. Deduce the dimensions of an unfamiliar quantity from a given relationship.	M, L, T, []	
	q2	Understand that some quantities are dimensionless.			
	q3	Be able to determine the units of a quantity by reference to its dimensions.	And vice versa.		
	q4	Be able to change the units in which a quantity is given.	E.g. density from kg m^{-3} to g cm^{-3} .		
	q5	Be able to use dimensional analysis to check the consistency of a relationship.			
Formulating and using models by means of dimensional arguments	q6	Use dimensional analysis to determine unknown indices in a proposed formula.	E.g. for the period of a pendulum.		
	q7	Use a model based on dimensional analysis.	E.g. to find the value of a dimensionless constant. E.g. to investigate the effect of a percentage change in some of the variables.		

Specification	Ref.	Learning outcomes	Notes	Notation	Exclusions
MECHANICS a: FORCES					
The language of forces	*	Understand the language relating to forces. Understand that the value of the normal reaction depends on the other forces acting and why it cannot be negative.	Weight, tension, thrust (or compression), normal reaction (or normal contact force), frictional force, resistance. Driving force, braking force ¹ . NB weight is not considered to be a resistive force.		
		¹ The driving force of a car, bicycle, train engine etc. is modelled as a single external force. Similarly for a braking force. These are actually frictional forces acting at the point(s) of contact with the road or track. The internal processes which cause these forces are not considered.			
Friction	Md1	† Understand that bodies in contact may be subject to a frictional force as well as a normal contact force (normal reaction), and be able to represent the situation in an appropriate force diagram.	Smooth is used to mean frictionless.		
	d2	† Understand that the total contact force between surfaces may be expressed in terms of a frictional force and a normal contact force (normal reaction).			
	d3	† Understand that the frictional force may be modelled by $F \leq \mu R$ and that friction acts in the direction to oppose sliding. Model friction using $F = \mu R$ when sliding occurs.	Limiting friction. The definition of μ as the ratio of the frictional force to the normal contact force.	Coefficient of friction is μ .	The term angle of friction.
	d4	Be able to derive and use the result that a body on a rough slope inclined at an angle α to the horizontal is on the point of slipping if $\mu = \tan \alpha$.			
	d5	† Be able to apply Newton's laws to situations involving friction.			
Vector treatment of forces	d6	† Be able to resolve a force into components and be able to select suitable directions for resolution.	E.g. horizontally and vertically, or parallel and perpendicular to an inclined plane.		
	d7	† Be able to find the resultant of several concurrent forces by vector addition.	Graphically or by adding components.		

Specification	Ref.	Learning outcomes	Notes	Notation	Exclusions
MECHANICS a: FORCES					
Equilibrium of a particle	Md8	† Know that a particle is in equilibrium under a set of concurrent forces if and only if their resultant is zero.			
	d9	† Know that a closed figure may be drawn to represent the addition of the forces on an object in equilibrium.	E.g. a triangle of forces.		
	d10	† Be able to formulate and solve equations for equilibrium by resolving forces in suitable directions, or by drawing and using a polygon of forces.	Questions will not be set that require Lami's theorem but learners may quote and use it where appropriate.		
Equilibrium of a rigid body	d11	Be able to draw a force diagram for a rigid body.	In cases where the particle model is not appropriate.		
	d12	Understand that a system of forces can have a turning effect on a rigid body.	E.g. a lever.		
	d13	Know the meaning of the term couple.	A couple is not about a particular axis.		
	d14	Be able to calculate the moments about a fixed axis of forces acting on a body. Be able to calculate the moment of a couple.	Both as the product of force and perpendicular distance of the axis from the line of action of the force, and by first resolving the force into components. Take account of a given couple when taking moments.		Vector treatment.
	d15	Understand and be able to apply the conditions for equilibrium of a rigid body.	The resultant of all the applied forces is zero and the sum of their moments about any axis is zero. Three forces in equilibrium must be concurrent or parallel. Situations may involve uniform 3-D objects, such as a cuboid, whose centre of mass can be written down by considering symmetry. E.g. infer the existence of a couple by consideration of equilibrium and calculate its size.		
	d16	Be able to identify whether equilibrium will be broken by sliding or toppling.	E.g. a cuboid on an inclined plane.		

Specification	Ref.	Learning outcomes	Notes	Notation	Exclusions
MECHANICS a: WORK, ENERGY AND POWER					
The language of work, energy and power	Mw1	Understand the language relating to work, energy and power.	Work, energy, mechanical energy, kinetic energy, potential energy, conservative force, dissipative force, driving force, resistive force Power of a force, power developed by a vehicle ¹ .		
	¹ In an examination question 'the power developed by a car' (or a bicycle or train engine) means the useful, or available, power. It is the power of the driving force; it is not the power developed by the engine, some of which is lost in the system.				
Concepts of work and energy	w2	Be able to calculate the work done by a force which moves along its line of action.			The use of calculus for variable forces.
	w3	Be able to calculate the work done by a force which moves at an angle to its line of action.	Zero work is done by a force acting perpendicular to displacement.		Use of scalar product F.s .
	w4	Be able to calculate kinetic energy.		$KE = \frac{1}{2}mv^2$	
	w5	Be able to calculate gravitational potential energy.	Relative to a defined zero level.	$GPE = mgh$	
The work-energy principle	w6	Understand when the principle of conservation of energy may be applied and be able to use it appropriately.	E.g. the maximum height of a projectile, a particle sliding down a smooth curved surface, a child swinging on a rope.		
	w7	Understand and use the work-energy principle.	The total work done by all the external forces acting on a body is equal to the increase in the kinetic energy of the body. E.g. a particle sliding down a rough curved surface.		
Power	w8	Understand and use the concept of the power of a force as the rate at which it does work.	Power = (force) \times (component of velocity in the direction of the force). The concept of average power as (work done) \div (elapsed time). E.g. finding the maximum speed of a vehicle.		

Specification	Ref.	Learning outcomes	Notes	Notation	Exclusions
MECHANICS a: MOMENTUM and IMPULSE					
Momentum and impulse treated as vectors	Mi1	Be able to calculate the impulse of a force as a vector and in component form.	Impulse = force \times time over which it acts.		The use of calculus for variable forces.
	i2	Understand and use the concept of linear momentum and appreciate that it is a vector quantity.			
	i3	Understand and use the impulse-momentum equation.	The total impulse of all the external forces acting on a body is equal to the change in momentum of the body. Use of relative velocity in one dimension is required.		
Conservation of linear momentum	i4	Understand and use the principle that a system subject to no external force has constant total linear momentum and that this result may be applied in any direction.	The impulse of a finite external force (e.g. friction) acting over a very short period of time (e.g. in a collision) may be regarded as negligible. Application to collisions, coalescence and a body dividing into one or more parts.		
Direct impact	i5	Understand the term direct impact and the assumptions made when modelling direct impact collisions ¹ .	E.g. a collision between an ice hockey puck and a straight rink barrier: puck moving perpendicular to barrier. E.g. a collision between two spheres moving along their line of centres. E.g. a collision between two railway trucks on a straight track.		Any situation with rotating objects.

¹Assumptions when modelling direct impact collisions

This note explains the implicit assumptions made in examination questions when modelling direct impact collisions. Learners may be asked about these assumptions. An *object* means a real-world object. It may be modelled as a *particle* or a *body*.

- If the non-fixed objects involved in collisions may be modelled as particles, then all the motion and any impulses due to the collisions act in the same straight line.
- If the non-fixed objects involved in collisions may be modelled as bodies, then these bodies will be uniform bodies with spherical or circular symmetry.
- The impulse of any collision between such bodies acts on the line joining their centres, and the motion takes place along this line.
These assumptions ensure that the collision happens at a point and that no angular momentum is created, hence none of the objects starts to rotate.
- The impulse of any collision between such a body, or a particle, and a plane (e.g. a wall or floor) acts in a direction perpendicular to the plane.
For a direct impact the motion of the object is also in the direction perpendicular to the plane.
- Objects do not rotate before or after the collision. Rotating objects are beyond this specification.

Specification	Ref.	Learning outcomes	Notes	Notation	Exclusions
MECHANICS a: MOMENTUM and IMPULSE					
Direct impact (cont)	Mi6	Be able to apply the principle of conservation of linear momentum to direct impacts within a system of bodies.			
	i7	Know the meanings of Newton's Experimental Law and of coefficient of restitution when applied to a direct impact.	Newton's Experimental Law is: the speed of separation is $e \times$ the speed of approach where e is known as the coefficient of restitution.	Coefficient of restitution is e .	
	i8	Understand the significance of $e = 0$.	The bodies coalesce. The collision is inelastic.		
	i9	Be able to apply Newton's Experimental Law in modelling direct impacts.	E.g. between a particle and a wall. E.g. between two discs.		
	i10	Be able to model situations involving direct impact using both conservation of linear momentum and Newton's Experimental Law.			
	i11	Understand the significance of $e = 1$.	The collision is perfectly elastic. Kinetic energy is conserved.		
	i12	Understand that when $e < 1$ kinetic energy is not conserved during impacts and be able to find the loss of kinetic energy.			

Specification	Ref.	Learning outcomes	Notes	Notation	Exclusions
MECHANICS a: CENTRE OF MASS					
Locating a centre of mass	MG1	Be able to find the centre of mass of a system of particles of given position and mass.	In 1, 2 and 3 dimensions.	$(\bar{x}, \bar{y}, \bar{z})$ $\left(\sum_i m_i\right)\bar{x} = \sum_i m_i x_i$	Non-uniform bodies.
	G2	Know how to locate centre of mass by appeal to symmetry.	E.g. uniform circular lamina, sphere, cuboid.		
	G3	Know the positions of the centres of mass of a uniform rod, a rectangular lamina and a triangular lamina.			
	G4	Be able to find the centre of mass of a composite body by considering each constituent part as a particle at its centre of mass.	Composite bodies may be formed by the addition or subtraction of parts. Where a composite body includes parts whose centre of mass the learner is not expected to know or be able to find, the centre of mass will be given.		
Applications of the centre of mass	G5	Be able to use the position of the centre of mass in situations involving the equilibrium of a rigid body.	For the purpose of calculating its moment, the weight of a body can be taken as acting through its centre of mass. E.g. a suspended object. E.g. does an object standing on an inclined plane slide or topple?		

2e. Content of Statistics a (Y412) – option

Description	In this option, situations are modelled by discrete random variables; the suitability of models is tested using χ^2 tests. Bivariate data are investigated, with tests for correlation and association and modelling using regression.
Assumed knowledge	Learners are expected to know the content of AS Level Mathematics and the Core Pure mandatory paper (Y410). The content can be co-taught with AS Level Mathematics.
Assessment	One examination paper
Length of paper	1 hour 15 minutes
Number of marks	60
Sections	The examination paper will not have sections.
Percentage of qualification	This optional paper counts for 33⅓% of the qualification OCR AS Level Further Mathematics B (MEI) (H635).
Use of calculator and other technology	See Section 2b for details about the use of calculators. Calculators used in the examination should be able to calculate means, standard deviations, correlation coefficients, equations of regression lines and probabilities, including cumulative probabilities, from the binomial and Poisson distributions. It is expected that learners will gain experience of using a spreadsheet or other software for exploring data sets; this should include using software to conduct hypothesis tests. In the examination, learners will be assessed on the interpretation of output from such software.
Overarching Themes	The Overarching Themes (see Section 2b) apply. Statistics is about answering real world problems using data, so knowledge of the real world appropriate to a learner on this course will be assumed. Examination questions may include, for example, asking learners to comment sensibly about the modelling assumptions in their answer.
Relationship with other papers	This option comprises the same content as Statistics Minor (Y432) and the same content as the sections labelled (a) in Statistics Major (Y422) in the qualification OCR A Level Further Mathematics B (MEI) (H645).
Other notes	When making calculations within a probability model, learners are advised to use exact numbers (e.g. fractions) where possible or decimal numbers to 4 dp. When interpreting solutions in a practical context, rounding to an appropriate (usually lesser) degree of accuracy is expected. Learners are expected to have explored different data sets, using appropriate technology, during the course. No particular data set is expected to be studied, and there will not be any pre-release data.

Statistics a (Y412)

Contents

Sampling	A short section about the importance of sampling methods.
Discrete random variables	The binomial distribution is introduced for modelling discrete univariate data in AS Level Mathematics. This content extends the range of models available to include the (discrete) uniform, geometric and Poisson distributions. The link between the binomial and Poisson distributions is explored, though the use of the Poisson as an approximation to the binomial distribution for calculation purposes is not included; technology renders it largely obsolete. Some theoretical work on discrete probability distributions, including mean and variance and some of their properties, is introduced and applied to these models.
Bivariate data	Different types of bivariate data are considered. Where appropriate, Pearson's product moment correlation coefficient and Spearman's rank correlation coefficient are used to test for correlation and association, respectively, for bivariate numerical data. The different underlying assumptions are explored. Linear regression as a model for bivariate numerical data is introduced; residuals provide an informal way of looking at the appropriateness of the model.
Chi-squared tests	The hypothesis testing work in AS Level Mathematics - based on the binomial distribution and, informally, on correlation coefficients - is extended in this unit to include χ^2 tests and a more formal approach to tests based on correlation coefficients. This gives learners an understanding of a range of tests, including the concept of degrees of freedom, which should allow them to pick up quickly any hypothesis tests they encounter in other subjects. The product moment correlation coefficient is also considered, informally, as an effect size; this serves as an example of a widely-used approach which is complementary to hypothesis testing. The χ^2 test for goodness of fit is used to test whether a particular distribution is appropriate to model a given data set. For bivariate categorical data, the χ^2 test for association, using data given in a contingency table, is introduced.

Specification	Ref.	Learning outcomes	Notes	Notation	Exclusions
STATISTICS a: SAMPLING					
Sampling	Sx1	Be able to explain the importance of sample size in experimental design.	E.g. an informal explanation of how the size of a sample affects the interpretation of an effect size.		
	x2	Be able to explain why sampling may be necessary in order to obtain information about a population, and give desirable features of a sample.	Population too large or it is too expensive to take a census. Sampling process may be destructive. Sample should be unbiased, representative of the population; data should be relevant, not changed by the act of sampling.	A sample may also be considered as n observations from a random variable.	
	x3	Be able to explain the advantage of using a random sample when inferring properties of a population.	A random sample enables proper inference to be undertaken because the probability basis on which the sample has been selected is known.		
STATISTICS a: DISCRETE RANDOM VARIABLES					
Probability distributions	SR1	Be able to use probability functions, given algebraically or in tables. Be able to calculate the numerical probabilities for a simple distribution. Be able to draw and interpret graphs representing probability distributions.	Other than the Poisson and geometric distributions, the underlying random variable will only take a finite number of values. An understanding that probabilities are non-negative and sum to 1 is expected.	$P(X = x)$	
Expectation and variance	R2	Be able to calculate the expectation (mean), $E(X)$, in simple cases and understand its meaning.		$E(X) = \mu$	
	R3	Be able to calculate the variance, $\text{Var}(X)$, in simple cases and understand its meaning.	Knowledge of $\text{Var}(X) = E(X^2) - \mu^2$. Standard deviation = $\sqrt{\text{Var}(X)}$.	$\text{Var}(X) = E[(X - \mu)^2]$	
	R4	Be able to use the result $E(a + bX) = a + bE(X)$ and understand its meaning.			
	R5	Be able to use the result $\text{Var}(a + bX) = b^2\text{Var}(X)$ and understand its meaning.			

Specification	Ref.	Learning outcomes	Notes	Notation	Exclusions
STATISTICS a: DISCRETE RANDOM VARIABLES					
Expectation and variance (cont)	SR6	Be able to find the expectation of any linear combination of independent random variables and the variance of any linear combination of independent random variables.	$E(X \pm Y) = E(X) \pm E(Y)$ $\text{Var}(X \pm Y) = \text{Var}(X) + \text{Var}(Y)$ $E(aX \pm bY) = aE(X) \pm bE(Y)$ $\text{Var}(aX \pm bY) = a^2 \text{Var}(X) + b^2 \text{Var}(Y)$		Proofs.
The discrete uniform distribution	R7	Recognise situations under which the discrete uniform distribution is likely to be an appropriate model.	E.g. X has a uniform distribution over the values $\{4, 5, 6, 7, 8, 9\}$. E.g. a fair spinner with six equally-sized sections, labelled 4, 5, 6, 7, 8, 9.		
	R8	Be able to calculate probabilities using a discrete uniform distribution.			
	R9	Be able to calculate the mean and variance of any given discrete uniform distribution.	If X has a uniform distribution over the values $\{1, 2, \dots, n\}$ then $E(X) = \frac{n+1}{2}$ and $\text{Var}(X) = \frac{1}{12}(n^2 - 1)$. The formulae for this particular uniform distribution will be given but their derivations may be asked for.		
The binomial distribution	R10	Recognise situations under which the binomial distribution is likely to be an appropriate model, and be able to calculate probabilities to use the model. Know and be able to use the mean and variance of a binomial distribution, $\mu = np$ and $\sigma^2 = np(1 - p)$. Prove these results in particular cases.	E.g. prove results by considering a binomial random variable as the sum of n independent Bernoulli random variables: $X = X_1 + X_2 + \dots + X_n$ where each X_i takes the value 1 with probability p and 0 with probability $1 - p$. This proof assumes the relationship about variance in SR6.	$X \sim B(n, p)$	

Specification	Ref.	Learning outcomes	Notes	Notation	Exclusions
STATISTICS a: DISCRETE RANDOM VARIABLES					
The Poisson distribution	SR11	Recognise situations under which the Poisson distribution is likely to be an appropriate model.	Modelling the number of events occurring in a fixed interval (of time or space) when the events occur randomly at a constant average rate, and independently of each other. It is expected that these conditions can be applied to the particular context. If the mean and variance of the data do not have a similar value then the Poisson model is unlikely to be suitable.	$X \sim \text{Po}(\lambda)$ $X \sim \text{Poisson}(\lambda)$	
	R12	Recognise situations in which both the Poisson distribution and the binomial distribution might be appropriate models.	In a situation where the binomial model is appropriate, if n is large and p is small, then the conditions for a Poisson distribution to be appropriate are approximately satisfied. In the absence of guidance either model can be used.		Formal criteria. Using the Poisson distribution as a numerical approximation for calculating binomial probabilities.
	R13	Be able to calculate probabilities using a Poisson distribution.	Including use of a calculator to access Poisson probabilities, and cumulative Poisson probabilities.		
	R14	Know and be able to use the mean and variance of a Poisson distribution.	$E(X) = \lambda, \text{Var}(X) = \lambda$		Proof.
	R15	Know that the sum of two or more independent Poisson distributions is also a Poisson distribution.	$X \sim \text{Po}(\lambda)$ and $Y \sim \text{Po}(\mu)$ $\Rightarrow X + Y \sim \text{Po}(\lambda + \mu)$ when X and Y are independent.		Proof.

Specification	Ref.	Learning outcomes	Notes	Notation	Exclusions
STATISTICS a: DISCRETE RANDOM VARIABLES					
The geometric distribution	SR16	Recognise situations under which the geometric distribution is likely to be an appropriate model.	Link with corresponding binomial distribution.	$X \sim \text{Geo}(p)$, where X = number of Bernoulli trials up to and including the first success.	The alternative definition which counts the number of failures.
	R17	Be able to calculate the probabilities within a geometric distribution, including cumulative probabilities.	$P(X = r) = (1 - p)^{r-1}p$ where p = probability of success and $r \in \{1, 2, \dots\}$. $P(X > r) = (1 - p)^r$. An understanding of the calculation is expected.		
	R18	Know and be able to use the mean and variance of a geometric distribution.	$E(X) = \frac{1}{p}$, $\text{Var}(X) = \frac{1-p}{p^2}$.		Proof.

Specification	Ref.	Learning outcomes	Notes	Notation	Exclusions
STATISTICS a: BIVARIATE DATA					
<p>There are two kinds of bivariate data considered in A Level Mathematics and Further Mathematics and it is important to distinguish between them when considering correlation and regression. This note explains the reason for the distinction; learners will only be assessed on what appears under a specification reference below.</p> <p>Case A: Only one of the variables may be considered as a random variable. Often this occurs when one of the variables, the independent variable, is controlled by an experimenter and the other, the dependent variable, is measured. An example of this would be (weight, extension) in an investigation of Hooke's Law for a spring. In this case, certain fixed weights are used; this variable is <i>not</i> a random variable, any errors in measuring the weights are negligible. The extension <i>is</i> a random variable. There will be deviations from the 'true' value that a perfect experimenter would observe from a perfect spring as well as errors in the measurement. This case is referred to as 'random on non-random'. The points on the scatter diagram are restricted to lie on certain vertical lines corresponding to the values of the controlled variable.</p> <p>Case B: The two variables may both be considered as random variables. An example of this would be (height, weight) for a sample from a population of individuals. For any given value of height there is a distribution of weights; for any given value of weight there is a distribution of heights. That is, there is no 'true' weight for a given height or 'true' height for a given weight. This case is referred to as 'random on random'. The scatter diagram appears as a 'data cloud'.</p> <p>If a linear relationship between the variables is to be investigated and modelled using correlation and regression techniques then the two cases must be treated differently.</p> <p>If it is desired to test the significance of Pearson's product moment correlation coefficient (pmcc) then, as with all parametric hypothesis tests, probability calculations have to be performed to calculate the p-value or the critical region. These calculations rely on certain assumptions about the underlying distribution – these assumptions can never be met in the 'random on non-random case' – because one of the variables does not have a probability distribution – so such a test is never valid in this case. In fact the pmcc is not used in this case. In the 'random on random' case the distributional assumptions may be met – see the specification below for details.</p> <p>If it is desired to calculate the equation of a line of best fit then the least-squares method is often used in both cases. However its interpretation is different in the two cases. In the example of the 'random on non-random' case, (weight, extension), the line of regression is modelling the 'true' value of the extension for a given weight – the value that a perfect experimenter would observe from a perfect spring. In the example of the 'random on random' case, (height, weight), the two lines of regression are modelling the mean value of the distribution of weights for a given height and the mean value of the distribution of heights for a given weight.</p>					

Specification	Ref.	Learning outcomes	Notes	Notation	Exclusions
STATISTICS a: BIVARIATE DATA					
Scatter diagrams	Sb1	Understand what bivariate data are and know the conventions for choice of axis for variables in a scatter diagram.	In the random on non-random case the independent variable is often one which the experimenter controls; the dependent variable is the one which is measured. The independent variable is usually plotted on the horizontal axis. In the random on random case (where both variables are measured), it may be that one is more naturally seen as a function of the other; this determines which variable is plotted on which axis.		
	b2	Be able to use and interpret a scatter diagram.	To look for outliers (by eye). To gain insight into the situation, for example, to decide whether a test for correlation or association might be appropriate. Learners may be asked to add to a given scatter diagram in order to interpret a new situation.		
	b3	Interpret a scatter diagram produced by software.	Including where the software draws a trendline and gives a value for pmcc or $(\text{pmcc})^2$.		
Pearson's product moment correlation coefficient (pmcc)	b4	Be able to calculate the pmcc from raw data or summary statistics.	Use of a calculator is expected for calculation from raw data. Summary statistics formulae given.	Sample value r .	
	b5	Know when it is appropriate to carry out a hypothesis test using Pearson's product moment correlation coefficient.	The data must be random on random i.e. both variables must be random. There must be a modelling assumption that the data are drawn from a bivariate Normal distribution. This may be recognised on a scatter diagram by an approximately elliptical distribution of points. Learners will not be required to know the formal meaning of bivariate Normality but will be expected to know that where one or both of the distributions is skewed, bimodal, etc., the procedure is likely to be inappropriate. The test is for correlation, a linear relationship, so a scatter diagram is helpful to check that the data cloud does not indicate a non-linear relationship.		

Specification	Ref.	Learning outcomes	Notes	Notation	Exclusions
STATISTICS a: BIVARIATE DATA					
Pearson's product moment correlation coefficient (pmcc) (cont)	Sb6	Be able to carry out hypothesis tests using the pmcc and tables of critical values or the p -value from software.	Only ' H_0 : No correlation in the population' will be tested. Both one-sided and two-sided alternative hypotheses will be tested. Learners should state whether there is sufficient evidence or not to reject H_0 and then give a non-assertive conclusion in context. E.g. 'There is sufficient evidence to suggest that there is positive correlation between ... and ...'	Null hypothesis, alternative hypothesis H_0 , H_1 .	
	b7	Use the pmcc as an effect size ¹ .	Sensible informal comments about effect size are expected, either alongside or instead of a hypothesis test.		Any formal rules for judging effect size will be given.
<p>¹Note on effect size for correlation</p> <p>For a large set of random on random bivariate data a small non-zero value of the pmcc is likely to lead to a rejection of the null hypothesis of no correlation in the population; the test is uninformative. In some contexts it is more important to consider the size of the correlation rather than test whether the population correlation is non-zero. The phrase 'effect size' is sometimes used in this context for the value of the pmcc. In social sciences, Cohen's guideline is often used: small effect size 0.1, medium effect size 0.3, large effect size 0.5. Learners are not expected to know this rule; this or any other formal rule will be given if necessary.</p> <p>Effect sizes for other situations, e.g. for the difference of two means, are beyond the scope of this specification.</p>					

Specification	Ref.	Learning outcomes	Notes	Notation	Exclusions
STATISTICS a: BIVARIATE DATA					
Spearman's rank correlation coefficient	Sb8	Be able to calculate Spearman's rank correlation coefficient from raw data or summary statistics.	Use of a calculator on the ranked data is expected.	Sample value r_s .	Tied ranks.
	b9	Be able to carry out hypothesis tests using Spearman's rank correlation coefficient and tables of critical values or the output from software.	Hypothesis tests using Spearman's rank correlation coefficient require no modelling assumptions about the underlying distribution. Only ' H_0 : No association in the population' will be tested. Both one-sided and two-sided alternative hypotheses will be tested. Learners should state whether there is sufficient evidence or not to reject H_0 and then give a non-assertive conclusion in context. E.g. 'There is insufficient evidence to suggest that there is an association between ... and ...'.		
Comparison of tests	b10	Decide whether a test based on r or r_s may be more appropriate, or whether neither is appropriate.	Considerations include the appearance of the scatter diagram, the likely validity of underlying assumptions, whether association or correlation is to be tested for. Spearman's test is not appropriate if the scatter diagram shows no evidence of a monotonic relationship i.e. one variable tends to increase (or decrease) as the other increases. Understanding that ranking data loses information, which may affect the outcome of a test.		

Specification	Ref.	Learning outcomes	Notes	Notation	Exclusions
STATISTICS a: BIVARIATE DATA					
Regression line for a random variable on a non-random variable	Sb11	Be able to calculate the equation of the least squares regression line using raw data or summary statistics.	The goodness of fit of a regression line may be judged by looking at the scatter diagram. In this case, examination questions will be confined to cases in which a random variable, Y , and a non-random variable, x , are modelled by a relationship in which the 'true' value of Y is a linear function of x . The use of a calculator is only expected for calculation from raw data. Summary statistics formulae will be given.		Derivation of the least squares regression line.
	b12	Be able to use the regression line as a model to estimate values and know when it is appropriate to do so. Know the meaning of the term residual and be able to calculate and interpret residuals.	residual = observed value – value from regression line. Informal checking of a model by looking at residuals.	Interpolation. Extrapolation.	
Regression lines for a random variable on a random variable	b13	Be able to calculate the equation of the two least squares regression lines, y on x and x on y , using raw data or summary statistics. Be able to use either regression line to estimate the expected value of one variable for a given value of the other and know when it is appropriate to do so.	In the y on x case, the least squares regression line estimates $E(Y X = x)$, that is the expected value of Y for a given value of X . Conversely for the x on y case. The use of a calculator is only expected for calculation from raw data.		Derivation of the least squares regression lines.
	b14	Check how well the model fits the data.	Informal checking only of a model by visual inspection of a scatter diagram or consideration of $(\rho_{mcc})^2$.		Residuals in this case.
	b15	Know the relationship between the two regression lines and when to use one rather than the other. Be able to use the correct regression line to estimate the expected value of one variable for a given value of the other and know when it is appropriate to do so.	Both lines pass through (\bar{x}, \bar{y}) . Choice of line to use depends on which variable is to be estimated.	Interpolation. Extrapolation.	

Specification	Ref.	Learning outcomes	Notes	Notation	Exclusions
STATISTICS a: CHI-SQUARED TESTS					
Contingency tables	Sb16	Be able to interpret bivariate categorical data in a contingency table.	Numerical data can be put into categories, but this loses information.		
χ^2 test for a contingency table	SH1	Be able to apply the χ^2 test (chi-squared) to a contingency table.	Only 'H ₀ : No association between the factors' or 'H ₀ : variables are independent' will be tested. Calculating degrees of freedom is expected. Knowing how to calculate observed values and contributions to the test statistic are expected, but repetitive calculations will not be required. Learners should state whether there is sufficient evidence or not to reject H ₀ and then give a non-assertive conclusion in context. E.g. 'There is not sufficient evidence to believe that there is association between ... and ...'.		Yates' continuity correction is not expected, though its appropriate use will not be penalised.
	H2	Be able to interpret the results of a χ^2 test using tables of critical values or the output from software.	Output from software may be given as a <i>p</i> -value. Interpretation may involve considering the individual cells in the table of contributions to the test statistic.		
χ^2 test for goodness of fit	H3	Be able to carry out a χ^2 test for goodness of fit of a uniform, binomial or Poisson model.	Only 'H ₀ : the given model fits the data' or 'H ₀ : the given model is suitable' will be tested. Calculating degrees of freedom is expected. Knowing how to calculate observed values and contributions to the test statistic is expected, but repetitive calculations will not be required. Learners should be aware that cells are often combined when there are small expected frequencies, but will not have to make such decisions in examination questions. Learners should state whether there is sufficient evidence or not to reject H ₀ and then give a non-assertive conclusion in context. E.g. 'It is reasonable to believe that the ... model is suitable'.		
	H4	Be able to interpret the results of a χ^2 test using tables of critical values or the output from software.	Output from software may be given as a <i>p</i> -value.		

2f. Content of Modelling with Algorithms (Y413) – option

Description	Algorithms play a central part in the modern world. This minor option explores algorithms in their own right. This is most easily done in cases in which the algorithm can be run by hand, but when algorithms are used to model real-world problems then technology allows their application to authentic problems. A range of optimisation and network problems are introduced. Many of these can be formulated as linear programming problems, allowing them to be solved using technology.
Assumed knowledge	For the examination learners are expected to know the content of AS Level Mathematics and the Core Pure mandatory paper (Y410). The content of the unit can be co-taught with AS Level Mathematics.
Assessment	One examination paper
Length of paper	1 hour 15 minutes
Number of marks	60
Sections	The examination paper will not have sections.
Percentage of qualification	This optional paper counts for 33⅓% of the qualification OCR AS Level Further Mathematics B (MEI) (H635).
Use of calculator and other technology	See Section 2b for details about the use of calculators. It is expected that learners will gain experience of using a spreadsheet solver or other software for solving linear programs; in the examination they will be assessed on the interpretation of output from such software.
Overarching Themes	The Overarching Themes (see Section 2b) apply. This content includes questions about modelling the real world, so knowledge of the real world appropriate to a learner on this course will be assumed. Examination questions may include, for example, asking learners to suggest why an answer which satisfies the mathematical model may not be acceptable in practice.
Relationship with other papers	This option comprises the same content as Modelling with Algorithms (Y433) in the qualification OCR A Level Further Mathematics B (MEI) (H645).
Other notes	When making calculations within a model, learners are advised to use exact numbers (e.g. fractions or surds) where possible. When interpreting solutions in a practical context, rounding to an appropriate degree of accuracy is expected.

Modelling with Algorithms (Y413)

Contents

Algorithms	In covering this section of the specification, learners should understand: what an algorithm is; iterative processes; what kind of problems are susceptible to an algorithmic approach; how to compare algorithms, including complexity; the importance of proving that an algorithm works and of the use of heuristic algorithms when this is not possible; the need for an algorithmic approach and computing power to solve problems of the size often met in the real world. Other algorithms are used for modelling in the Networks section; this section emphasises that algorithms can be analysed in their own right.
Networks	Network algorithms are used for modelling a range of real-world problems. Formulating the problems as LP problems allows them to be addressed using technology.
Linear Programming (LP)	This topic introduces constrained optimisation. In some cases LP problems can be interpreted and solved graphically. The simplex method gives an algebraic approach, but using this by hand is limited. The use of a simplex method optimisation routine in a spreadsheet package or other software is introduced, which enables problems of a more realistic size to be tackled. The crucial skills are then setting up the problem in a way suitable for the software and interpreting the output. These are precisely the modelling skills most useful in the real world. Linear programming unifies this content; a wide range of apparently unrelated problems can be formulated as LP problems, and so solved using technology.

This division of the specification is not a recommended division of the material for teaching or assessment. It would be quite sensible, for example to: introduce a particular network algorithm, using it by hand in suitable cases; where appropriate analyse its complexity and prove that it works; use it for modelling and solving problems; and then formulate it as an LP problem and use technology to tackle authentic problems. The division of the specification is designed to emphasise that this unit is much more than a collection of algorithms chosen because they are accessible at this level.

Specification	Ref.	Learning outcomes	Notes	Notation	Exclusions
MODELLING WITH ALGORITHMS: ALGORITHMS					
Algorithms	A1	Understand that an algorithm is a finite sequence of operations for carrying out a procedure or solving a problem. Understand that an algorithm can be the basis for a computer program.	Initial state; input; output; variable. 'Finite' means that the procedure terminates.		Algorithms with a random element.
	A2	Be able to interpret and apply algorithms presented in a variety of formats.	Formats include flowcharts; written English; pseudocode. E.g. in pseudocode, Let $i = i + 1$ means that the number in location i is replaced by its current value plus 1. Questions will not be set requiring unduly repetitive calculations.	Loop, pass. 'if ... then...' 'Go to step ...' Iterative process.	Any particular version of pseudocode or programming language.
	A3	Be able to repair, develop and adapt given algorithms.			
	A4	Understand and be able to use the basic ideas of algorithmic complexity and be able to analyse the complexity of given algorithms. Know that complexity can be used, among other things, to compare algorithms.	Worst case; size of problem; effect on solution time of multiplying the size of a large problem by a given factor and/or repeatedly applying an algorithm.	Order notation e.g. $O(n^2)$ for quadratic complexity.	Analysis leading to non-polynomial complexity.
	A5	Understand that algorithms can sometimes be proved correct or incorrect.	Proof by exhaustion and disproof by counter-example.		

Specification	Ref.	Learning outcomes	Notes	Notation	Exclusions
MODELLING WITH ALGORITHMS: ALGORITHMS					
Algorithms (cont)	A6	Understand and know the importance of heuristics.	A heuristic (sometimes called a heuristic algorithm) is a method which finds a solution efficiently, with no guarantee that it is optimal. It is important when classic methods are inefficient or fail.	E.g. packing algorithms. E.g. find a solution to a linear problem which requires an integer solution by exploring around the solution to the corresponding LP.	
Sorting algorithms	A7	Know and be able to use the quick sort algorithm. Be able to apply other sorting algorithms which are specified.		Pivot values. Pass. Ascending, descending.	
	A8	Be able to count the number of comparisons and/or swaps needed in particular applications of sorting algorithms, and relate this to complexity.	Quick sort algorithm has (worst case) complexity $O(n^2)$.		Average complexity.
	A9	Be able to reason about a given sorting algorithm.	E.g. explain why it will always work.		
Packing algorithms	A10	Know and be able to use first fit and first fit decreasing packing algorithms and full bin strategies.	Know that these are not guaranteed to be optimal.	Bin.	
	A11	Be able to count the number of comparisons needed in particular applications of packing algorithms, and relate this to complexity.	First fit and first fit decreasing algorithms have (worst case) complexity $O(n^2)$.		

Specification	Ref.	Learning outcomes	Notes	Notation	Exclusions
MODELLING WITH ALGORITHMS: NETWORKS					
Networks and graphs	N1	Understand and be able to use graphs and associated language.	Node/vertex; arc/edge; tree; order of a node; simple, complete, connected and bipartite graphs; trees; digraphs.	Incidence matrix.	
	N2	Be able to model problems by using graphs.	E.g. river crossing problems. E.g. matching problems.		
	N3	Understand that a network is a graph with weighted arcs.	Directed and undirected networks.		
	N4	Be able to model problems by using networks.	E.g. shortest path, maximum flow. E.g. allocation and transportation problems.		
Kruskal's, Prim's and Dijkstra's algorithms	N5	Be able to solve minimum connector problems using Kruskal's and Prim's algorithms.	Kruskal's algorithm in graphical form only. Prim's algorithm in graphical or tabular form.	Minimum spanning tree.	
	N6	Model shortest path problems and solve using Dijkstra's algorithm.			
	N7	Know and use the fact that Kruskal's, Prim's and Dijkstra's algorithms have quadratic complexity.	Kruskal's and Prim's have $O(n^2)$ as a function of the number of edges. Dijkstra's has $O(n^2)$ as a function of the number of vertices.		
Critical path analysis	N8	Model precedence problems with an activity-on-arc network.			
	N9	Use critical path analysis and be able to interpret outcomes, including implications for criticality. Be able to analyse float (total, independent and interfering), resourcing and scheduling.	E.g. show how to use the minimum number of people to complete a given project in the minimum time.	Critical activities, critical path(s), forward and backward passes, longest path.	

Specification	Ref.	Learning outcomes	Notes	Notation	Exclusions
MODELLING WITH ALGORITHMS: NETWORKS					
Network flows	N10	Be able to use a network to model a transmission system.	Single and super sources and sinks. Flow in = flow out for other nodes.	Source: S. Sink: T.	
	N11	Be able to specify a cut and calculate its capacity.	<i>Either</i> split the vertices into two sets, one containing S and the other T, <i>or</i> specify the arcs that are cut.		
	N12	Understand and use the maximum flow/minimum cut theorem.	If an established flow is equal to the capacity of an identified cut, then the flow is maximal and the cut is a minimum cut. Exhaustive testing of cuts will not be assessed.		Flow augmentation. Labelling algorithm.
Solving network problems using technology	N13	Understand that network algorithms can be explored, understood and tested in cases in which the algorithm can be run by hand, but for practical problems the algorithm needs to be formulated in a way suitable for computing power to be applied.	Formulations will be restricted to LPs. Questions may be set about the time taken by computer software to implement an algorithm when its complexity is known.		

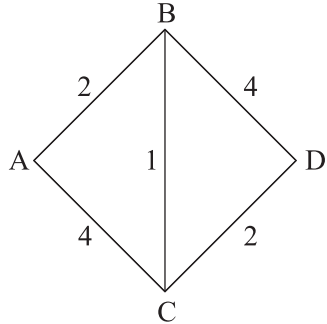
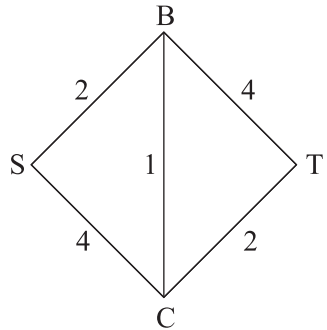
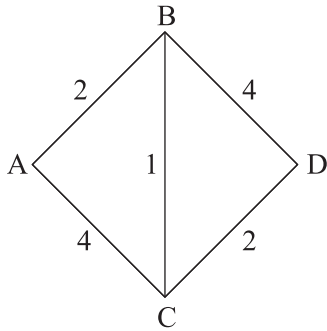
Specification	Ref.	Learning outcomes	Notes	Notation	Exclusions
MODELLING WITH ALGORITHMS: LINEAR PROGRAMMING					
Formulating a problem	AL1	Understand and use the language associated with linear programming.	Linear programming, objective, maximisation, minimisation, optimisation, constraints.	LP is an abbreviation for linear program.	
	L2	Be able to identify and define variables from a given problem. Be able to formulate a problem as a linear program.	Variables should be clearly identified as representing numerical values. E.g. 'Let x be the number of ...'. Problem may be given in context.		
	L3	Be able to recognise when an LP is in standard form.	A linear function to be maximised, constraints with ' $\dots \leq \text{constant}$ ' and non-negative, continuous variables.		
	L4	Be able to use slack variables to convert an LP in standard form to augmented form.	Also called slack form. As standard form, but using non-negative slack variables to convert inequalities to equalities.	State variables. Slack variables. Basic and non-basic variables.	
	L5	Recognise when an LP requires an integer solution.	E.g. when a variable is discrete. E.g. a shortest path problem, because the variables take the values 1 or 0, depending on whether the corresponding arc is in the path or not. If an LP requires an integer solution this should be stated in the formulation.	ILP is an abbreviation for integer LP.	
	L6	Be able to formulate a range of network problems as LPs.	Shortest path problems; network flows; critical path (longest path) problems; matching, allocation and transportation problems. See after L18 for examples.		

Specification	Ref.	Learning outcomes	Notes	Notation	Exclusions
MODELLING WITH ALGORITHMS: LINEAR PROGRAMMING					
Graphical solution of an LP	L7	Be able to graph inequalities in 2-D and identify feasible regions. Be able to recognise infeasibility.	No particular shading convention is expected, but learners must make clear which is the feasible region.		Drawing diagrams in more than 2-D.
	L8	Be able to solve a 2-D LP graphically.	By finding at least one optimal feasible point and the value of the objective function at this point. Using the gradient of the objective function or by enumeration.		
	L9	Be able to consider the effect of modifying constraints or the objective function.		Post-optimal analysis.	
	L10	Be able to solve simple 2-D integer LP problems graphically.	The optimal lattice point may or may not be near the LP solution.		
	L11	Be able to use a visualisation of a 3-D LP to solve it. Be able to reduce a 3-D LP to a 2-D LP when one constraint is an equality.	Diagram will be given. Regions will be defined by an inequality based on the cartesian equation of a plane.		
Simplex method	L12	Be able to use the simplex algorithm on an LP in augmented form.	Setting up an initial tableau, choosing a pivot, transforming the tableau, interpreting a tableau, recognising when a tableau represents an optimal solution. Problems may be infeasible or have multiple solutions (degeneracy).	Initial, intermediate, final tableau. Slack variables. Pivot. Basic/non-basic variables.	Knowledge of complexity of the simplex algorithm.
	L13	Understand the geometric basis for the simplex method.	Interpret a tableau in terms of the vertex and value of the objective function.		

Specification	Ref.	Learning outcomes	Notes	Notation	Exclusions
MODELLING WITH ALGORITHMS: LINEAR PROGRAMMING					
Simplex and non-standard form	L14	Recognise that if an LP includes \geq constraints then the two-stage simplex method may be used; understand how this method works and be able to set up the initial tableau in such cases.			Big-M method.
	L15	Be able to reformulate an equality constraint as a pair of inequality constraints.	E.g. replace $x = 4$ by $x \geq 4$ and $x \leq 4$.		
	L16	Recognise that if an LP has variables which may take negative values or requires the objective function to be minimised then some initial reformulation is required before the simplex algorithm may be applied.	Learners need only know that such reformulation is possible.		Be able to apply simplex in these situations.
Use of software	L17	Understand that some LPs can be solved using graphical techniques or the simplex method, but for practical problems computing power needs to be applied. Know that a spreadsheet LP solver routine, or other software, can solve an LP given in standard form or, in some cases, in non-standard form.			
	L18	Be able to interpret the output from a spreadsheet optimisation routine, or other software, for the simplex method or ILPs.	Select the appropriate information to solve the original problem. This may lead to further analysis of the problem.		

Examples of reformulating network problems as LPs

These examples show how six types of network problems can be reformulated as LPs. They illustrate the sort of notation that will be used in questions. They do not show the level of difficulty of problems that will be examined.

	<p>Shortest path Find a shortest path from A to D. Variables take the value 1 if the corresponding arc is used in a shortest path, and 0 otherwise.</p>		<p>Minimise $2AB + 4BD + 4AC + 2CD + BC + CB$ subject to $AB + AC = 1$ $AB + CB - BC - BD = 0$ $AC + BC - CB - CD = 0$ $BD + CD = 1$</p>
	<p>Network flow Find a maximum flow from S to T through the network.</p>		<p>Maximise $SB + SC$ subject to $SB + CB - BC - BT = 0$ $SC + BC - CB - CT = 0$ $SB \leq 2$ $BT \leq 4$ $SC \leq 4$ $CT \leq 2$ $BC \leq 1$ $CB \leq 1$</p>
	<p>Longest path Find a longest path from A to D. Variables take the value 1 if the corresponding arc is used in a shortest path, and 0 otherwise. This can be used to solve critical path problems on a directed network.</p>		<p>Maximise $2AB + 4BD + 4AC + 2CD + BC + CB$ subject to $AB + AC = 1$ $AB + CB - BC - BD = 0$ $AC + BC - CB - CD = 0$ $BD + CD = 1$ $AB \leq 1$ $BD \leq 1$ $AC \leq 1$ $CD \leq 1$ $BC \leq 1$ $CB \leq 1$</p>

	<p>Matching problem Possible associations between elements of $\{A, B, C, D\}$ and $\{1, 2, 3, 4\}$ are shown in the table. In a matching each element of one set is associated with at most one element of the other. The LP tries to find a maximal matching, i.e. a matching with as many associations as possible. Each variable (e.g. C_3) takes the value 1 (if C and 3 are associated) or 0.</p>	<table border="1" style="margin-left: auto; margin-right: auto;"> <thead> <tr> <th></th> <th>1</th> <th>2</th> <th>3</th> <th>4</th> </tr> </thead> <tbody> <tr> <th>A</th> <td>x</td> <td></td> <td></td> <td>x</td> </tr> <tr> <th>B</th> <td>x</td> <td></td> <td>x</td> <td></td> </tr> <tr> <th>C</th> <td></td> <td>x</td> <td>x</td> <td></td> </tr> <tr> <th>D</th> <td></td> <td></td> <td>x</td> <td></td> </tr> </tbody> </table> <p>“x” indicates a possible matching</p>		1	2	3	4	A	x			x	B	x		x		C		x	x		D			x		<p>Maximise $A_1 + A_4 + B_1 + B_3 + C_2 + C_3 + D_3$ subject to $A_1 + A_4 \leq 1$ $B_1 + B_3 \leq 1$ $C_2 + C_3 \leq 1$ $D_3 \leq 1$ $A_1 + B_1 \leq 1$ $C_2 \leq 1$ $B_3 + C_3 + D_3 \leq 1$ $A_4 \leq 1$</p>											
	1	2	3	4																																			
A	x			x																																			
B	x		x																																				
C		x	x																																				
D			x																																				
	<p>Allocation problem This is like a matching problem, except that (usually) every association is possible, and each association has a cost. The LP minimises the total cost for a maximal matching. Each variable (e.g. A_1) takes the value 1 or 0, depending on whether A is associated with 1 or not in the matching.</p>	<table border="1" style="margin-left: auto; margin-right: auto;"> <thead> <tr> <th></th> <th>1</th> <th>2</th> <th>3</th> <th>4</th> </tr> </thead> <tbody> <tr> <th>A</th> <td>5</td> <td>2</td> <td>3</td> <td>6</td> </tr> <tr> <th>B</th> <td>1</td> <td>7</td> <td>2</td> <td>4</td> </tr> <tr> <th>C</th> <td>5</td> <td>8</td> <td>3</td> <td>1</td> </tr> <tr> <th>D</th> <td>4</td> <td>4</td> <td>2</td> <td>6</td> </tr> </tbody> </table>		1	2	3	4	A	5	2	3	6	B	1	7	2	4	C	5	8	3	1	D	4	4	2	6	<p>Minimise $5A_1 + 2A_2 + 3A_3 + 6A_4 + B_1 + 7B_2 + 2B_3 + 4B_4 + 5C_1 + 8C_2 + 3C_3 + C_4 + 4D_1 + 4D_2 + 2D_3 + 6D_4$ subject to $A_1 + A_2 + A_3 + A_4 = 1$ $B_1 + B_2 + B_3 + B_4 = 1$ $C_1 + C_2 + C_3 + C_4 = 1$ $D_1 + D_2 + D_3 + D_4 = 1$ $A_1 + B_1 + C_1 + D_1 = 1$ $A_2 + B_2 + C_2 + D_2 = 1$ $A_3 + B_3 + C_3 + D_3 = 1$ $A_4 + B_4 + C_4 + D_4 = 1$</p>											
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B	1	7	2	4																																			
C	5	8	3	1																																			
D	4	4	2	6																																			
	<p>Transportation problem The body of the table shows the costs per item of transporting from one set of locations $\{A, B, C, D\}$ to another $\{1, 2, 3, 4\}$. The margins show the availability of items at locations A, B, C and D and the demands at 1, 2, 3 and 4. The LP minimises the total cost of delivering all the required items.</p>	<table border="1" style="margin-left: auto; margin-right: auto;"> <thead> <tr> <th></th> <th></th> <th>5</th> <th>5</th> <th>5</th> <th>5</th> </tr> <tr> <th></th> <th></th> <th>1</th> <th>2</th> <th>3</th> <th>4</th> </tr> </thead> <tbody> <tr> <th>3</th> <th>A</th> <td>5</td> <td>2</td> <td>3</td> <td>6</td> </tr> <tr> <th>6</th> <th>B</th> <td>1</td> <td>7</td> <td>2</td> <td>4</td> </tr> <tr> <th>9</th> <th>C</th> <td>5</td> <td>8</td> <td>3</td> <td>1</td> </tr> <tr> <th>2</th> <th>D</th> <td>4</td> <td>4</td> <td>2</td> <td>6</td> </tr> </tbody> </table>			5	5	5	5			1	2	3	4	3	A	5	2	3	6	6	B	1	7	2	4	9	C	5	8	3	1	2	D	4	4	2	6	<p>Minimise $5A_1 + 2A_2 + 3A_3 + 6A_4 + B_1 + 7B_2 + 2B_3 + 4B_4 + 5C_1 + 8C_2 + 3C_3 + C_4 + 4D_1 + 4D_2 + 2D_3 + 6D_4$ subject to $A_1 + A_2 + A_3 + A_4 = 3$ $B_1 + B_2 + B_3 + B_4 = 6$ $C_1 + C_2 + C_3 + C_4 = 9$ $D_1 + D_2 + D_3 + D_4 = 2$ $A_1 + B_1 + C_1 + D_1 = 5$ $A_2 + B_2 + C_2 + D_2 = 5$ $A_3 + B_3 + C_3 + D_3 = 5$ $A_4 + B_4 + C_4 + D_4 = 5$</p>
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9	C	5	8	3	1																																		
2	D	4	4	2	6																																		

2g. Content of Numerical Methods (Y414) – option

Description	Much of AS/A Level Mathematics and AS Level Further Mathematics is restricted to problems which are amenable to exact solution. For many real-world problems no exact methods exist, and numerical methods are required to solve them. In this option, learners apply numerical approaches to four topics from mathematics: solution of equations, differentiation, integration and approximating functions. Learners learn how to use a spreadsheet to implement the methods and learn to analyse the errors associated with numerical methods.
Assumed knowledge	For the examination, learners are expected to know the content of AS Level Mathematics and the Core Pure mandatory paper (Y410). The content can be co-taught with AS Level Mathematics.
Assessment	One examination paper
Length of paper	1 hour 15 minutes
Number of marks	60
Sections	The examination paper will not have sections.
Percentage of qualification	This optional paper counts for 33⅓% of the qualification OCR AS Level Further Mathematics B (MEI) (H635).
Use of calculator and other technology	It is expected that a calculator is used in the examination. See Section 2b for details about the use of calculators, but note that capabilities such as numerical differentiation, numerical integration and equation solvers should not be used in the examination; learners must show sufficient working to make their method clear. It is expected that learners will gain experience of using a spreadsheet for implementing numerical methods; in the examination, learners may be given output from spreadsheets and may be asked: to explain what certain cells represent; to explain or give formulae for certain cells; to give solutions and justify their accuracy; to comment on errors, convergence or order.
Overarching Themes	The Overarching Themes (see Section 2b) apply. Questions may be set requiring learners to model a real world situation, and then use numerical methods to solve the mathematics before interpreting the solution; learners may be asked to comment on the error due to the numerical method employed as well as the appropriateness of the model.
Relationship with other papers	This option comprises the same content as Numerical Methods (Y434) in the qualification OCR A Level Further Mathematics B (MEI) (H645).
Other notes	N/A

Numerical Methods (Y414)**Contents**

Use of technology	This section describes how spreadsheets and calculators are to be used.
Errors	Dealing with errors is tackled in this section; how they arise and propagate and how analysis of errors can lead to improved solutions.
Solution of equations	Five methods for solving equations are studied, with their graphical interpretation: bisection method; false position; secant method; fixed point iteration and Newton-Raphson. Failure and order of convergence is considered. The method of relaxation is applied to fixed point iteration.
Numerical differentiation	Two methods are studied and compared: forward difference method and central difference method.
Numerical integration	Three methods are studied and the relationships between them exploited: midpoint, trapezium and Simpson's methods.
Approximation to functions	Two methods are studied, including the circumstances in which each is appropriate: Newton's forward difference interpolation method and Lagrange's form of the interpolating polynomial.

Specification	Ref.	Learning outcomes	Notes	Notation	Exclusions
NUMERICAL METHODS: USE OF TECHNOLOGY					
Use of spreadsheets and calculators	NQ1	Be able to use a spreadsheet to implement the methods in this unit and to explore associated ideas. Be able to interpret the output from a spreadsheet.	Learners are expected to be familiar with a spreadsheet; no particular one is expected. In the examination, the spreadsheet facility available on some calculators may be used, but this is not expected. Learners will be given output from a spreadsheet and may be asked to explain what certain cells represent, to explain or give formulae for certain cells, to give solutions and justify their accuracy, to comment on errors, convergence or order.	Cell B4 will mean the cell in column B, row 4. =IF(condition, value_if_true, value_if_false). Learners may give formulae from any spreadsheet with which they are familiar.	Use of a computer in the examination.
	Q2	Be able to use the iterative capability of a calculator.	In the examination, learners are expected to use the iterative capabilities of their calculators (e.g. the ANS button) to generate values of iterative sequences. Any permitted calculator may be used, but capabilities such as numerical differentiation, numerical integration and equation solvers should not be used in the examination for this unit; learners must show sufficient working to make their method clear. Lengthy calculations will not be required.		

Specification	Ref.	Learning outcomes	Notes	Notation	Exclusions
NUMERICAL METHODS: ERRORS					
Absolute and relative error	NU1	Know how to calculate errors in sums, differences, products and quotients. Know the meaning of absolute and relative error.	Exact value: x Approximate value: X Absolute error: $X - x$ Relative error: $\frac{X - x}{x}$.		Absolute error will be used as a signed quantity. Another convention defines absolute error to be the magnitude of this quantity; this usage will not be penalised.
Error propagation by arithmetical operations and by functions	U2	Know how to calculate the error in $f(x)$ when there is an error in x .			Functions of more than one variable.
	U3	Understand the effects on errors of changing the order of a sequence of operations.			
Errors in the representation of numbers: rounding; chopping	U4	Understand that computers represent numbers to limited precision.			
	U5	Understand the consequences of subtracting nearly equal quantities.	The subtraction might be embedded within a more complicated calculation e.g. in a fraction or in solving simultaneous equations.		
	U6	Understand rounding and chopping and their consequences, including for calculations.	E.g. 7.86 rounded to 1 d.p. is 7.9; 7.86 chopped to 1 d.p. is 7.8; 5.7 chopped to the nearest integer is 5. E.g. 200 numbers are each expressed to 1 d.p. Each number is chopped to the nearest integer, and then they are added. Maximum error in any one number is 0.9; maximum error in sum is $200 \times 0.9 = 180$. Average error in one number is 0.45, so expected error for sum is 90.	Maximum, average and expected error.	

Specification	Ref.	Learning outcomes	Notes	Notation	Exclusions
NUMERICAL METHODS: ERRORS					
Order of convergence and order of method	NU7	Understand convergence and divergence when applied to sequences. Understand the order of convergence of an iterative sequence and the order of a method. Be able to comment on these given outputs from a spreadsheet.	An iterative sequence (e.g. a sequence produced by the Newton-Raphson method) has k th order convergence if the sequence of errors \mathcal{E}_n satisfy the approximate relationship $\mathcal{E}_{n+1} \propto \mathcal{E}_n^k$. For a method with a 'step-length' h , (e.g. central difference method), the order of the method is the value k such that, approximately, error $\propto h^k$. (For such a method a sequence of approximations can be produced by using a sequence of values of h ; the sequence of errors will have an order of convergence, but this is not , in general, the order of the method.)		Formal analysis e.g. using Taylor expansions.
Improving a solution	U8	Be able to use error analysis to produce an improved solution.	Learners may be expected to calculate or identify the ratio of differences of a sequence of approximations to, for example, a definite integral. This may be presented as part of a spreadsheet output. They should be able to use an appropriate value for the ratio of differences to obtain an improved approximation by extrapolation – including to infinity - and should be able to quote and justify an appropriate level of precision in their final answer.		

Specification	Ref.	Learning outcomes	Notes	Notation	Exclusions
NUMERICAL METHODS: SOLUTION OF EQUATIONS					
Bisection method; False Position (linear interpolation); Secant method; Fixed point iteration; Newton-Raphson method	Ne1	Understand the graphical interpretations of these methods.	Including staircase and cobweb diagrams. Learners should be able to comment on suitability of starting point.		Proofs of orders of convergence.
	e2	Be able to solve equations to any required degree of accuracy using these methods.	Justify the accuracy claimed.		
	e3	Understand the relative computational merits and possible failure of these methods.	Learners should recognise situations in which fixed point iteration and Newton-Raphson methods will fail.		
	e4	Know that fixed point iteration generally has first order convergence, Newton-Raphson generally has second order convergence.	Learners should be able to comment on failure of the method or lower-order convergence from graphical considerations or from spreadsheet output: e.g. the relationship between the order of convergence and the gradient of $g(x)$ at the root in the iteration $x_{n+1} = g(x_n)$.		Formal proofs of convergence. Formal analysis of failure or lower-order convergence.
	e5	Understand and be able to apply relaxation to a fixed point iteration: to accelerate convergence; to convert a divergent sequence to a convergent sequence.	For the iteration $x_{n+1} = g(x_n)$ the relaxed iteration is $x_{n+1} = (1 - \lambda)x_n + \lambda g(x_n)$. Formula will be given. Different values of λ have different effects on convergence.		Calculus to find optimal choice for λ .

Specification	Ref.	Learning outcomes	Notes	Notation	Exclusions
NUMERICAL METHODS: NUMERICAL DIFFERENTIATION					
Forward difference method; Central difference method	Nc1	Be able to estimate a derivative using the forward and central difference methods with a suitable value (or sequence of values) of h .	Use a suitable sequence of values of h to observe when the limitation of a spreadsheet's accuracy is reached, to analyse errors and to justify the accuracy of a solution.	$f'(x) \approx \frac{f(x+h) - f(x)}{h}$ $f'(x) \approx \frac{f(x+h) - f(x-h)}{2h}$	Second derivatives.
	c2	Have an empirical and graphical appreciation of the greater accuracy of the central difference method. Know that the forward difference method is generally a first order method and that the central difference method is generally a second order method.			Proofs of order of method.

Specification	Ref.	Learning outcomes	Notes	Notation	Exclusions
NUMERICAL METHODS: NUMERICAL INTEGRATION					
Midpoint rule; trapezium rule; Simpson's rule	Nc3	Be able to evaluate a given definite integral to any desired degree of accuracy using these methods.	<p>To estimate $\int_a^b f(x) dx$:</p> $M_n = h(y_{\frac{1}{2}} + y_{\frac{3}{2}} + \dots + y_{n-\frac{3}{2}} + y_{n-\frac{1}{2}}) \quad \text{where } h = \frac{b-a}{n}$ $T_n = \frac{1}{2}h\{(y_0 + y_n) + 2(y_1 + y_2 + \dots + y_{n-1})\} \quad \text{where } h = \frac{b-a}{n}$ $S_{2n} = \frac{1}{3}h\{(y_0 + y_{2n}) + 4(y_1 + y_3 + \dots + y_{2n-1}) + 2(y_2 + y_4 + \dots + y_{2n-2})\}$ <p style="text-align: right;">where $h = \frac{b-a}{2n}$.</p> <p>These formulae will be given. Lengthy calculations will not be required in the examination.</p> <p>Any of the rules may be applied more than once, e.g. with h halving each time.</p> <p>Learners are expected to be able to consider properties of the function – e.g. the graph is concave upwards over the given interval – to determine whether the rule over- or under- estimates.</p>	N.B. The commonly used notation for Simpson's rule, S_{2n} , shown in the formula, leads to an inconsistent definition of h . M_n will be referred to as the midpoint rule based on n strips; T_n will be referred to as the trapezium rule based on n strips; the concept of strips will not be applied to Simpson's rule.	
The relationship between methods	c4	Know that, generally, the midpoint and trapezium rules are second order methods and Simpson's rule is a fourth order method. Understand the development of Simpson's rule from the midpoint and trapezium rules.	$T_{2n} = \frac{1}{2}(M_n + T_n)$ $S_{2n} = \frac{1}{3}(2M_n + T_n) = \frac{1}{3}(4T_{2n} - T_n)$ <p>Formulae will be given.</p>		

Specification	Ref.	Learning outcomes	Notes	Notation	Exclusions
NUMERICAL METHODS: APPROXIMATIONS TO FUNCTIONS					
Newton's forward difference interpolation method	Nf1	Be able to use Newton's forward difference interpolation formula to reconstruct polynomials and to approximate functions.	Functions tabulated at equal intervals; learners should recognise when this is not the case and the method is not suitable. Formula will be given. Learners should be able to construct and use a difference table and know that n th differences are constant for an n th degree polynomial.	$\Delta f(x) = f(x+h) - f(x)$ $\Delta^2 f(x) = \Delta f(x+h) - \Delta f(x)$	
Lagrange's form of the interpolating polynomial	f2	Be able to construct the interpolating polynomial of degree n given a set of $n + 1$ data points.	Formula will be given.		

2h. Content of Mechanics b (Y415) – option

Description	In this option, the content of Mechanics a (Y411) is extended to include oblique impact collisions, circular motion, Hooke's Law, centres of mass in the continuous case and variable forces. It is permitted that learners enter for Mechanics b (Y415) without entering for Mechanics a (Y411), but this content dependency should be noted.
Assumed knowledge	Learners are expected to know the content of AS Level Mathematics and Core Pure (Y410) as well as the following sections from the content of Mechanics a (Y411); Forces; Work, energy and power; Momentum and impulse; Centre of mass. Learners are expected to be able to model motion under gravity in a vertical plane; this content is from A Level Mathematics.
Assessment	One examination paper
Length of paper	1 hour 15 minutes
Number of marks	60
Sections	The examination paper will not have sections.
Percentage of qualification	This optional paper counts for 33⅓% of the qualification OCR AS Level Further Mathematics B (MEI) (H635).
Use of calculator and other technology	See Section 2b for details about the use of calculators.
Overarching Themes	The Overarching Themes (see Section 2b) apply. Mechanics is about modelling the real world, so knowledge of the real world appropriate to a learner on this course will be assumed. Examination questions may include, for example, asking learners to suggest an explanation for a discrepancy between the results of a class experiment and the theoretical answer they have obtained; learners are expected to comment sensibly about the modelling assumptions in their answer.
Relationship with other papers	This content comprises the same content as the shaded sections, labelled (b), in Mechanics Major (Y421) in the qualification OCR A Level Further Mathematics B (MEI) (H645).
Other notes	<p>The acceleration due to gravity is denoted by $g \text{ m s}^{-2}$. Unless otherwise instructed, when a numerical value is needed, learners should use $g = 9.8$.</p> <p>When making calculations within a model, learners are advised to use exact numbers (e.g. fractions or surds) where possible. When interpreting solutions in a practical context, rounding to an appropriate degree of accuracy is expected.</p> <p>† refers to content which overlaps or depends on non-AS content from A Level Mathematics.</p>

Mechanics b (Y415)
Contents

Momentum and impulse	The work on collisions is extended to oblique impact.
Circular motion	Circular motion with uniform and non-uniform speed is modelled using Newton's laws in the radial and tangential directions and using energy principles.
Hooke's Law	The motion of a particle attached to a spring or string is modelled using forces and energy conservation.
Centre of mass	The work on centre of mass is extended, using calculus, to include more general laminas and bodies formed by rotating a region about an axis.
Vectors and variable forces	Calculus is applied to situations in more than 1-dimension with constant and non-constant acceleration. Situations involving projectile motion are modelled, including motion up an inclined plane. Differential equation models are considered, including the special case of simple harmonic motion.

Specification	Ref.	Learning outcomes	Notes	Notation	Exclusions
MECHANICS b: MOMENTUM and IMPULSE					
Oblique impact	Mi13	Understand the term oblique impact and the assumptions made when modelling oblique impact collisions ¹ .	E.g. a collision between a sphere and a surface when the sphere is moving in a direction which is not perpendicular to the surface. E.g. a collision between two discs not moving along their lines of centres.		Any situation with rotating objects.
	i14	Know the meanings of Newton's Experimental Law and of coefficient of restitution when applied to an oblique impact.	The coefficient of restitution is the ratio of the components of the velocities of separation and approach, in the direction of the line of impulse.		
	i15	Be able to model situations involving oblique impact between an object and a smooth plane by considering the components of its motion parallel and perpendicular to the line of impulse.			
	i16	Be able to model situations involving oblique impact between two bodies by considering the components of their motion in directions parallel and perpendicular to the line of the impulse.			
	i17	Be able to calculate the loss of kinetic energy in an oblique impact.			

¹Assumptions when modelling oblique impact collisions

This note explains the implicit assumptions made in examination questions when modelling oblique impact collisions. Learners may be asked about these assumptions. When two objects collide obliquely they cannot be modelled as particles; with two particles there is no preferred direction to act as the line of impulse. If an object collides with a plane (e.g. a wall or a floor) then it may be modelled as a particle or as a body, as appropriate.

- If the non-fixed objects involved in collisions may be modelled as bodies, then these bodies will be uniform bodies with spherical or circular symmetry.
- The impulse of any collision between such bodies acts on the line joining their centres.
These assumptions ensure that the collision happens at a point and that no angular momentum is created, hence none of the objects starts to rotate. An oblique impact collision occurs when the line of relative motion of the bodies is not the same as the line joining their centres at the point of collision.
- The impulse of any collision between such a body, or a particle, and a plane (e.g. a wall or floor) acts in a direction perpendicular to the plane.
An oblique impact collision in this situation means that the motion of the object is not in the direction perpendicular to the plane.
- The contact between the surfaces in any collision is smooth.
This is an extra assumption for oblique collisions. It ensures that the linear momentum of each object is conserved in the direction perpendicular to the line of impulse.
- Objects do not rotate before or after the collision. Rotating objects are beyond this specification.

Specification	Ref.	Learning outcomes	Notes	Notation	Exclusions
MECHANICS b: CIRCULAR MOTION					
The language of circular motion	Mr1	Understand the language associated with circular motion.	The terms: tangential, radial and angular velocity; radial component of acceleration.	$\dot{\theta}$, ω for angular velocity. $v = r\dot{\theta}$ or $r\omega$.	Angular velocity as a vector.
Modelling circular motion	r2	Identify the force(s) acting on a body in circular motion.	Learners will be expected to set up equations of motion.		
	r3	Be able to calculate acceleration towards the centre of circular motion.	Using the expressions $\frac{v^2}{r}$ and $r\dot{\theta}^2$.		
Circular motion with uniform speed	r4	Be able to model situations involving circular motion with uniform speed in a horizontal plane.	E.g. a conical pendulum, a car travelling horizontally on a cambered circular track.		
Circular motion with non-uniform speed	r5	Be able to model situations involving circular motion with non-uniform speed.	E.g. rotation in a horizontal circle with non-uniform angular velocity.		
	r6	Be able to calculate tangential acceleration.	Tangential component of acceleration = $r\ddot{\theta}$. Use of Newton's 2nd Law, $F = ma$, in the tangential direction.		
	r7	Be able to model situations involving motion in a vertical circle.	The use of conservation of energy, and of $F = ma$ in the radial and tangential directions. E.g. sliding on the interior or exterior surface of a sphere.		
	r8	Identify the conditions under which a particle departs from circular motion.	E.g. when a string becomes slack, when a particle leaves a surface. Questions may ask about the subsequent motion.		

Specification	Ref.	Learning outcomes	Notes	Notation	Exclusions
MECHANICS b: HOOKE'S LAW					
The language of elasticity	Mh1	Understand the language associated with elasticity.	Modulus of elasticity, stiffness, natural length, string, spring, equilibrium position.		
	h2	Understand that Hooke's Law models the extension/compression of a material as a linear function of tension/thrust.		$T = kx$ where k is the stiffness.	
Extension of an elastic string and extension or compression of a spring.	h3	Be able to calculate the stiffness or modulus of elasticity in a given situation.			
	h4	Be able to calculate the tension in an elastic string or spring.		$T = \frac{\lambda x}{l_0}$ where λ is the modulus of elasticity and l_0 the natural length.	
	h5	Be able to calculate the equilibrium position of a system involving elastic strings or springs.	E.g. a heavy object suspended by a spring.		
	h6	Be able to calculate energy stored in a string or spring.	The proof of this result may include the use of calculus. (This is an exception to the exclusion in Mw2.)	$\frac{1}{2} \frac{\lambda x^2}{l_0}$ or $\frac{1}{2} kx^2$.	
	h7	Be able to use energy principles to model a system involving elastic strings or springs including determining extreme positions.	Applications to maximum extension for given starting conditions in a system, whether horizontal or vertical.		
	h8	Understand when Hooke's Law is not applicable.	Hooke's Law does not apply when the relationship between extension/compression and tension/thrust for a material is not linear. Many materials obey Hooke's Law for a limited range of tensions/thrusts but extend/compress in a non-linear way for high values of tension/thrust.		

Specification	Ref.	Learning outcomes	Notes	Notation	Exclusions
MECHANICS b: CENTRE OF MASS					
Use of calculus to find centre of mass	MG6	† Be able to calculate the volume generated by rotating a plane region about an axis.	Rotation about the x - and y - axes only.		Non-cartesian coordinates.
	G7	Be able to use calculus methods to calculate the centre of mass of solid bodies formed by rotating a plane region about an axis.	E.g. hemisphere, cone.		Variable density. Pappus' theorem.
	G8	Be able to find the centre of mass of a compound body, parts of which are solids of revolution.	By treatment as equivalent to a finite system of particles.		
	G9	Be able to use calculus methods to calculate the centre of mass of a plane lamina.			Pappus' theorem.
	G10	Be able to use the position of the centre of mass in situations involving the equilibrium of a rigid body.	For the purpose of calculating its moment, the weight of a body can be taken as acting through its centre of mass. E.g. a suspended object. E.g. does an object standing on an inclined plane slide or topple?		

Specification	Ref.	Learning outcomes	Notes	Notation	Exclusions
MECHANICS b: VECTORS AND VARIABLE FORCES					
The language of kinematics	Mk1	<p>† Understand the language of kinematics appropriate to motion in 2- and 3-dimensions. Know the distinction between displacement and distance, between velocity and speed, and between acceleration and magnitude of acceleration.</p> <p>Know the distinction between distance from and distance travelled.</p>	Position vector, relative position.	$\mathbf{a} = \dot{\mathbf{v}} = \frac{d\mathbf{v}}{dt}, \mathbf{v} = \dot{\mathbf{r}} = \frac{d\mathbf{r}}{dt}$ $\mathbf{r} = \int \mathbf{v} dt, \mathbf{v} = \int \mathbf{a} dt$ $\mathbf{s} = \mathbf{u}t + \frac{1}{2}\mathbf{a}t^2$ $\mathbf{s} = \mathbf{v}t - \frac{1}{2}\mathbf{a}t^2$ $\mathbf{v} = \mathbf{u} + \mathbf{a}t$ $\mathbf{s} = \frac{1}{2}(\mathbf{u} + \mathbf{v})t$	Vector form of $v^2 - u^2 = 2as$.
Velocity and position vector	k2	† Be able to extend the scope of techniques from motion in 1 dimension to that in 2 and 3 dimensions by using vectors.	Using calculus and constant acceleration formulae.		
	Mv1	Be able to find the acceleration, velocity and position vector of a particle subject to a constant or variable force in 1, 2 and 3 dimensions.	In terms of time or other parameters of a situation.		
	v2	Be able to use the acceleration, velocity and position vector of a particle to model situations in 1, 2 and 3 dimensions.	Including inferring the force acting.		

Specification	Ref.	Learning outcomes	Notes	Notation	Exclusions
MECHANICS b: VECTORS AND VARIABLE FORCES					
The equation of the path of a particle in 2D	Mv3	Be able to eliminate a parameter from the expressions for the position vector of a particle, thereby forming a single equation.	E.g. elimination of time. Questions will be restricted to cases where the elimination is straightforward.		
	v4	Be able to interpret the equation resulting from the elimination of a parameter from the terms of a position vector.	E.g. a bounding parabola. E.g. solving for x or solving for $\tan \alpha$ and interpreting.		
	v5	Derive the cartesian equation of the path of a particle in 2 dimensions from an expression for its position vector.	E.g. the trajectory of a projectile.		
	v6	Be able to find the range of a projectile up or down a uniform slope.	Only cases where the projectile's initial position is on the slope. Appropriate use of coordinates parallel and perpendicular to the slope, or horizontal and vertical. Standard modelling assumptions for projectile motion are as follows. <ul style="list-style-type: none"> No air resistance. The projectile is a particle. Horizontal distance travelled is small enough to assume that gravity is always in the same direction. Vertical distance travelled is small enough to assume that gravity is constant. 		
	v7	Be able to find the maximum range of a projectile up or down a uniform slope, and the associated angle of projection.	Only cases where the projectile's initial position is on the slope.		

Specification	Ref.	Learning outcomes	Notes	Notation	Exclusions
MECHANICS b: VECTORS AND VARIABLE FORCES					
Differential equations	Mv8	Be able to formulate differential equations for motion under variable acceleration in 1 and 2 dimensions.	E.g. use Hooke's Law for a particle on a spring or a particle attached to two springs to establish simple harmonic motion (SHM). E.g. establish that SHM applies to part of the motion of a particle. E.g. establish approximate SHM for a simple pendulum. E.g. when resistance is a given function of velocity. Including use of $a = v \frac{dv}{ds}$.		
	v9	Be able to verify a general or particular solution of a differential equation for motion under variable acceleration.	In the particular case this requires both showing that the solution is compatible with the equation and also that it conforms to the boundary or initial conditions for the situation when they are known.		Solving a differential equation, other than writing down a solution to SHM as in v12.
	v10	Be able to use the boundary or initial conditions to produce a particular solution from a general solution.			
	v11	Be able to recognise and formulate the simple harmonic motion equation expressed in non-standard forms and to transform it into the standard form by means of substitution.	E.g. $\ddot{x} + cx = 0$, $\ddot{x} = -\omega^2(x + k)$ where x can represent a variable such as an angle.		
	v12	Be able to solve the equation for simple harmonic motion, $\ddot{x} = -\omega^2x$, and be able to relate the solution to the context.	Learners may state that they recognise the differential equation is that for SHM, and quote the solution in an appropriate form (e.g. $p \cos(\omega t) + q \sin(\omega t)$, $A \sin(\omega t - \phi)$ or $A \cos(\omega t - \epsilon)$)	$ A = \sqrt{p^2 + q^2} =$ amplitude. $T = \text{period} = \frac{2\pi}{\omega}$ $v^2 = \omega^2(A^2 - x^2)$	

2i. Content of Statistics b (Y416) – option

Description	In this option, the content of Statistics a (Y412) is extended to include, continuous random variables, confidence intervals and some further hypothesis tests, and simulation. It is permitted that learners enter for Statistics b (Y416) without entering for Statistics a (Y412), but this content dependency should be noted.
Assumed knowledge	Learners are expected to know the content of AS Level Mathematics and Core Pure (Y410) as well as the following sections from Statistics a (Y412); Sampling; Discrete random variables; the concept of degrees of freedom from Chi-squared tests. Learners are expected to know how to use the Normal Distribution as a model, use it to calculate probabilities and to conduct a hypothesis test for a single mean; this content is from A Level Mathematics.
Assessment	One examination paper
Length of paper	1 hour 15 minutes
Number of marks	60
Sections	The examination paper will not have sections.
Percentage of qualification	This optional paper counts for 33⅓% of the qualification OCR AS Level Further Mathematics B (MEI) (H635).
Use of calculator and other technology	See Section 2b for details about the use of calculators. It is expected that learners will gain experience of using a spreadsheet or other software for exploring data sets; this should include using software to conduct hypothesis tests and construct confidence intervals. In the examination, learners will be assessed on the interpretation of output from such software. It is expected that learners will gain experience of using a spreadsheet for simulating a random variable; in the examination, they will be assessed on the interpretation of output from such software. Calculators used in the examination should be able to calculate means, standard deviations, correlation coefficients, equations of regression lines and probabilities, including cumulative probabilities, from the binomial and Poisson distributions.
Overarching Themes	The Overarching Themes (see Section 2b) apply. Statistics is about answering real world problems using data, so knowledge of the real world appropriate to a learner on this course will be assumed. Examination questions may include, for example, asking learners to comment sensibly about the modelling assumptions in their answer.
Relationship with other papers	This content comprises the same content as the shaded sections, labelled (b), in Statistics Major (Y422) in the qualification OCR A Level Further Mathematics B (MEI) (H645).
Other notes	When making calculations within a probability model, learners are advised to use exact numbers (e.g. fractions) where possible or decimal numbers to 4 dp. When interpreting solutions in a practical context, rounding to an appropriate (usually lesser) degree of accuracy is expected. Learners are expected to have explored different data sets, using appropriate technology, during the course. No particular data set is expected to be studied, and there will not be any pre-release data.

Statistics b (Y416) Contents

Continuous random variables (b)	The general work on discrete random variables is now extended to continuous random variables. The Normal distribution work in A Level Mathematics is taken further; the Normal probability plot is used to check whether a Normal model may be appropriate; a χ^2 test could be used for this but other tests specific to the Normal distribution are more widely used and are available on a good spreadsheet or other statistical software. The Central Limit Theorem provides another reason for the importance of the Normal distribution. Other continuous models are looked at in less detail.
Inference (b)	The focus here is on constructing and interpreting confidence intervals, rather than on hypothesis testing, which has been addressed in earlier work. The Normal and the t distributions are used for single sample, two-sample and paired sample confidence intervals. Three hypothesis tests for the average of a population are introduced, a Normal test, a t test and a Wilcoxon single sample test; these illustrate when non-parametric methods may be useful.
Simulation (b)	Many of the ideas in this unit can be explored using spreadsheet simulation of random variables and results can be obtained for which the theory is technically difficult. Examination questions will include interpreting spreadsheet output from simulations.

Specification	Ref.	Learning outcomes	Notes	Notation	Exclusions
STATISTICS b: CONTINUOUS RANDOM VARIABLES					
The probability density function (pdf) of a continuous random variable	SR19	Be able to use a continuous random variable as a model.	Learners are expected to be familiar with the use of the (continuous) uniform and Normal distributions as models. They should be aware that other distributions underpin some work in this unit e.g. t_n , χ_n^2 and that other distributions, such as the exponential distribution, are useful models; knowledge of these is not expected and any necessary details will be provided in the examination.	Continuous uniform distribution also known as rectangular distribution.	Mixed discrete and continuous random variables.
	R20	Understand the meaning of a pdf and be able to use one to find probabilities.	Unfamiliar pdf's, including piecewise pdf's, may be given in examination questions. In numerical cases, learners are expected to write down the relevant definite integral, and may then use a calculator to evaluate it.	$f(x)$ or other lower case letter for the function.	Using formula for pdf of Normal distribution.
	R21	Know and use the properties of a pdf. Be able to sketch the graph of a pdf.	$f(x) \geq 0$ and $\int_{-\infty}^{\infty} f(x) dx = 1$.		Evaluation of improper integrals.

Specification	Ref.	Learning outcomes	Notes	Notation	Exclusions
STATISTICS b: CONTINUOUS RANDOM VARIABLES					
The probability density function (pdf) of a continuous random variable (cont)	SR22	Be able to find the mean and variance from a given pdf.	Learners are expected to write down the relevant definite integral, and may then use a calculator to evaluate it. In examination questions, any integrations to be performed will be over a finite domain. Standard deviation = $\sqrt{\text{Var}(X)}$. For a continuous uniform distribution over $[a, b]$: $E(X) = \frac{a+b}{2}$, $\text{Var}(X) = \frac{1}{12}(b-a)^2$. Formulae will be given but derivations may be required.		Deriving mean and variance of the Normal distribution from the pdf. Evaluation of improper integrals.
	R23	Be able to find the mode and median from a given pdf.	Mode only where it exists.		Mode for bimodal distributions.
The cumulative distribution function (cdf)	R24	Understand the meaning of a cdf and be able to obtain one from a given pdf. Be able to sketch a cdf.	$F(x) = \int_{-\infty}^x f(t) dt$	$F(x)$ or other upper case letter for the function.	Normal distribution. Evaluation of improper integrals.
	R25	Be able to obtain a pdf from a given cdf.	$f(x) = F'(x)$		
	R26	Use a cdf to calculate the median and other percentiles.			
Expectation algebra	R27	Be able to find the mean of any linear combination of random variables and the variance of any linear combination of independent random variables.	$E(X \pm Y) = E(X) \pm E(Y)$ $\text{Var}(X \pm Y) = \text{Var}(X) + \text{Var}(Y)$ $E(aX \pm bY) = aE(X) \pm bE(Y)$ $\text{Var}(aX \pm bY) = a^2\text{Var}(X) + b^2\text{Var}(Y)$		Proofs.

Specification	Ref.	Learning outcomes	Notes	Notation	Exclusions
STATISTICS b: CONTINUOUS RANDOM VARIABLES					
The Normal distribution	SR28	†Be able to use the Normal distribution as a model, and to calculate and use probabilities from a Normal distribution.	Calculations of probabilities are to be done using statistical functions on a calculator. Relate calculations of probabilities to the graph of the Normal distribution.		
	R29	Be able to use linear combinations of independent Normal random variables in solving problems.	Use the fact that if $X \sim N(\mu_x, \sigma_x^2)$ and $Y \sim N(\mu_y, \sigma_y^2)$, with X and Y independent, then $aX + bY \sim N(a\mu_x + b\mu_y, a^2\sigma_x^2 + b^2\sigma_y^2)$. Extend to more than two random variables.		Proof.
	R30	Know that the Normal distribution is useful as a model in its own right, and as an approximating distribution in the context of the Central Limit Theorem (CLT).	Includes recognising when the Normal distribution is not appropriate. Details of the CLT are in SI1 to SI6 below.		
	R31	Interpret a Normal probability plot to decide whether a Normal model might be appropriate ¹ . Interpret software output, including p -value, from the Kolmogorov-Smirnov test, to decide whether a Normal model might be appropriate.	Learners should know that tests other than the χ^2 test of goodness of fit are often applied to the Normal distribution. The null hypothesis for the given test is 'H ₀ : the Normal distribution fits the data'.		χ^2 test for goodness of fit of Normal distribution. Calculations for Kolmogorov-Smirnov test.
	R32	Be able to use the Normal distribution, when appropriate, in the construction of confidence intervals.	See SI7 to SI14 below for details.		

¹There are different conventions for how Normal probability plots are drawn, and different features about the underlying distribution, for example skewness, can be inferred from the plot. Learners are only expected to know that the closer the points are to a straight line, the more likely it is that a Normal distribution fits the data; this is to be judged by eye. They are not expected to be able to draw Normal probability plots, nor do any calculations. In the examination the sample data will be shown on one axis and the other will show expected Normal values.

Specification	Ref.	Learning outcomes	Notes	Notation	Exclusions
STATISTICS b: INFERENCE					
Distribution of sample mean and the Central Limit Theorem (CLT)	S11	Be able to estimate population mean from sample data.	This is a point estimate; see confidence intervals below for interval estimates.	$\hat{\mu} = \bar{x}$	Proof.
	12	Be able to estimate population variance using the sample variance.	Sample variance given by $s^2 = \frac{1}{n-1} \sum_{i=1}^n (x_i - \bar{x})^2$.		Proof.
	13	Understand that the sample mean is a random variable with a probability distribution.	If n independent observations X_1, X_2, \dots, X_n are taken from a distribution with mean μ and variance σ^2 then $\bar{X} = \frac{X_1 + X_2 + \dots + X_n}{n}$ is a random variable with a probability distribution. Using the results of SR6 and SR27 the mean of this distribution is μ and its variance is $\frac{\sigma^2}{n}$.	Sampling distribution of the mean.	
	14	Be able to calculate and interpret the standard error of the mean.	The 'standard error of the mean' is the standard deviation of the sampling distribution of the mean. It is equal to $\frac{\sigma}{\sqrt{n}}$. If σ is not known then it may be estimated from a particular sample as $\frac{s}{\sqrt{n}}$; this estimate is also sometimes referred to as the 'standard error of the mean'.		
	15	Know that if the underlying distribution is Normal then the sample mean is Normally distributed.	Using the results of SR29.		
	16	Understand how and when the Central Limit Theorem may be applied to the distribution of sample means. Use this result in probability calculations, using a continuity correction where appropriate. Be able to apply the CLT to the sum of n identically distributed independent random variables.	If X has a mean and finite variance, whatever its underlying distribution, the distribution of the sample mean \bar{X} may be approximated by a Normal distribution if n is sufficiently large; $n > 30$ is often used as a rule of thumb for 'sufficiently large'.		Formal statement and derivation of the CLT. Distributions for which the CLT does not apply.

Specification	Ref.	Learning outcomes	Notes	Notation	Exclusions
STATISTICS b: INFERENCE					
Confidence intervals using the Normal and t distributions	S17	Know the meaning of the term confidence interval for a parameter and associated language.	A <i>confidence interval</i> is an interval estimate for a population parameter, based on a sample. If the confidence interval is constructed a large number of times, based on independent samples, then the <i>confidence level</i> is the long run proportion of confidence intervals which contain the true value of the parameter.		Asymmetric confidence intervals. One-sided confidence intervals.
	18	Understand the factors which affect the width of a confidence interval.	Sample size, confidence level, population variability.		
	19	Be able to construct and interpret a confidence interval for a single population mean using the Normal or t distributions and know when it is appropriate to do so.	Use the Normal distribution when the sample size is large, using s^2 as an estimate for σ^2 if necessary. For a small sample from an underlying Normal distribution: <ul style="list-style-type: none"> if the population variance is known use the Normal distribution; if the population variance is unknown use the t distribution, with s^2 as an estimate for σ^2 with $n - 1$ degrees of freedom. 		
	110	Know when samples from two populations should be considered as paired.			
	111	Be able to construct and interpret a confidence interval for the difference in mean of two paired populations using a paired sample and a Normal or t distribution; know when it is appropriate to do so.	Treat the differences as a single distribution and construct a confidence interval for the mean of the differences using the same procedure as for a single mean. It is rarely the case that the population variance for the differences is known; this possibility will not be examined.		

Specification	Ref.	Learning outcomes	Notes	Notation	Exclusions
STATISTICS b: INFERENCE					
	SI12	Interpret confidence intervals given by software.	May include confidence intervals from distributions with which learners are not familiar; necessary details will be given.		
	I13	Use a confidence interval for a population parameter to make a decision about a hypothesised value of that parameter.	By checking whether the confidence interval contains the hypothesised value.		

Specification	Ref.	Learning outcomes	Notes	Notation	Exclusions
STATISTICS b: INFERENCE					
Hypothesis testing for an average using Wilcoxon, Normal or t tests	SH5	Be able to carry out a hypothesis test for a single population median using the Wilcoxon signed rank test and know when it is appropriate to do so.	Learners are expected to know that this is an example of a non-parametric (or distribution-free) hypothesis test, and when such tests may be useful. Underlying distribution needs to be symmetrical. H_0 : population median is given value. Both one-sided and two-sided alternative hypotheses will be tested. Learners should state whether there is sufficient evidence or not to reject H_0 and then give a non-assertive conclusion in context. E.g. 'There is not sufficient evidence to believe that the median ... has changed'.	W_+ the sum of the ranks for positive differences. W_- the sum of the ranks for negative differences.	
	SH6	Be able to carry out a hypothesis test for a single population mean using the Normal or t distributions and know when it is appropriate to do so.	Use the Normal distribution when the sample size is large, using s^2 as an estimate for σ^2 if necessary. For a small sample from an underlying Normal distribution: <ul style="list-style-type: none"> if the population variance is known use the Normal distribution; if the population variance is unknown use the t distribution, with s^2 as an estimate for σ^2 with $n - 1$ degrees of freedom. H_0 : population mean is given value. Both one-sided and two-sided alternative hypotheses will be tested. Learners should state whether there is sufficient evidence or not to reject H_0 and then give a non-assertive conclusion in context. E.g. 'There is sufficient evidence to believe that the mean... is not ...'.		

Specification	Ref.	Learning outcomes	Notes	Notation	Exclusions
STATISTICS b: SIMULATION					
Simulation of random variables	SZ1	Know that spreadsheets can be used to simulate probability distributions, and be able to do so for discrete and continuous uniform distributions and Normal distributions.	Learners are expected to appreciate the variation which repeated sampling produces.		
	Z2	Know that simulations can be used to approximate probability distributions and to estimate probabilities, including in situations where the theory may be technically difficult. Be able to interpret output from spreadsheets investigating such situations.	<p>E.g. if X and Y are independent random numbers from $[0, 1]$, estimate $P(2X - Y > 0)$.</p> <p>E.g. investigate the CLT for the sample mean from a continuous uniform distribution for various values of the sample size, n.</p> <p>E.g. investigate whether the result about linear combinations of independent Normal random variables holds in different cases.</p> <p>E.g. estimate the probability that 10 dice give a total score of greater than 50.</p> <p>E.g. I commute to and from work on trains which run every 15 minutes. If I arrive at the station at a random time between trains, what is the probability that I have to wait for more than 20 minutes in total on any one day?</p> <p>Learners will be expected to interpret output from spreadsheets to investigate such scenarios.</p>		

2j. Prior knowledge, learning and progression

It is assumed that learners are familiar with the content of GCSE (9–1) Mathematics for first teaching from 2015 and AS Level Mathematics for first teaching from 2017. There is no requirement that learners have completed these qualifications.

The content of Mechanics b (Y415) also builds on some of the skills, knowledge and understanding set out in the content of Mechanics a (Y411). It is permitted that learners enter for Mechanics b (Y415) without entering for Mechanics a (Y411), but this content dependency should be noted. Mechanics b (Y415) also builds on some of the content of A Level Mathematics not in AS Mathematics. Further details may be found at the beginning of section 2h.

The content of Statistics b (Y416) also builds on some of the skills, knowledge and understanding set out in the content of Statistics a (Y412). It is permitted that learners enter for Statistics b (Y416) without entering for Statistics a (Y412), but this content dependency should be noted. Statistics b (Y412) also builds on some of the content of A Level Mathematics not in AS Mathematics. Further details may be found at the beginning of section 2i.

Some learners may wish to follow a further mathematics course only up to AS Level, in order to broaden and deepen their curriculum, and to develop their interest and understanding of different areas of the subject. Others may follow a co-teachable route, completing a one-year AS course and then continuing to complete the second year of the two-year A Level course, developing a deeper knowledge and understanding of mathematics and its applications.

OCR AS Level in Further Mathematics B (MEI) is designed for learners with an enthusiasm for mathematics, many of whom will go on to degrees in mathematics, engineering, the sciences and economics, or any subject where mathematics is developed further than in A Level Mathematics.

AS Level Further Mathematics B (MEI), which can be co-taught with A Level Further Mathematics B (MEI) as a separate qualification and which can be taught alongside AS or A Level Mathematics, is a very useful qualification in its own right. It broadens and reinforces the content of AS and A Level Mathematics, introduces complex numbers and matrices, and gives learners the opportunity to extend their knowledge in applied mathematics and logical reasoning. This breadth and depth of study is very valuable for supporting the transition to degree level work and employment in mathematical disciplines.

The co-teachability of AS Level Further Mathematics B (MEI) and A Level Further Mathematics B (MEI) is made possible by the following links:

- The AS options Modelling with Algorithms and Numerical Methods each correspond to a minor option in the A Level with the same content.
- The AS options Mechanics a and Statistics a each correspond to an A Level minor option with the same content; this is the same content as the unshaded content, labelled (a), in the major option in the A Level.
- The AS options Mechanics b and Statistics b each have the same content as the shaded content, labelled (b), in the major option in the A Level.
- The AS Core Pure content has the same content as one third of the A Level Core Pure unit, shaded and labelled (a).

There are a number of Mathematics specifications at OCR. Find out more at www.ocr.org.uk

3 Assessment of AS Level in Further Mathematics B (MEI)

3a. Forms of assessment

OCR AS Level in Further Mathematics B (MEI) is externally assessed by written examination. All the papers may contain some synoptic assessment and some extended response questions.

Each paper is worth 33⅓% of the total AS Level. All questions within each examination paper are mandatory and there are 60 marks in total. Each paper will have a gradient of difficulty.

Core Pure (Y410) is a mandatory paper.

The optional papers are

- Mechanics a (Y411)
- Statistics a (Y412)
- Modelling with Algorithms (Y413)
- Numerical Methods (Y414)
- Mechanics b (Y415)
- Statistics b (Y416)

3b. Assessment objectives (AO)

There are three Assessment Objectives in OCR AS Level Further Mathematics B (MEI). These are detailed in the table below.

Learners are expected to demonstrate their ability to:

Assessment Objectives	
AO1	<p>Use and apply standard techniques</p> <p>Learners should be able to:</p> <ul style="list-style-type: none"> • select and correctly carry out routine procedures; and • accurately recall facts, terminology and definitions.
AO2	<p>Reason, interpret and communicate mathematically</p> <p>Learners should be able to:</p> <ul style="list-style-type: none"> • construct rigorous mathematical arguments (including proofs); • make deductions and inferences; • assess the validity of mathematical arguments; • explain their reasoning; and • use mathematical language and notation correctly. <p><i>Where questions/tasks targeting this assessment objective will also credit Learners for the ability to 'use and apply standard techniques' (AO1) and/or to 'solve problems within mathematics and in other contexts' (AO3) an appropriate proportion of the marks for the question/task will be attributed to the corresponding assessment objective(s).</i></p>
AO3	<p>Solve problems within mathematics and in other contexts</p> <p>Learners should be able to:</p> <ul style="list-style-type: none"> • translate problems in mathematical and non-mathematical contexts into mathematical processes; • interpret solutions to problems in their original context, and, where appropriate, evaluate their accuracy and limitations; • translate situations in context into mathematical models; • use mathematical models; and • evaluate the outcomes of modelling in context, recognise the limitations of models and, where appropriate, explain how to refine them. <p><i>Where questions/tasks targeting this assessment objective will also credit Learners for the ability to 'use and apply standard techniques' (AO1) and/or to 'reason, interpret and communicate mathematically' (AO2) an appropriate proportion of the marks for the question/task will be attributed to the corresponding assessment objective(s).</i></p>

AO weightings in AS Level in Further Mathematics B (MEI)

The relationship between the Assessment Objectives and the examination papers are shown in the following table:

	% weighting of unit in qualification	% weighting of AOs for each unit		
		AO1	AO2	AO3
Core Pure	33⅓	60	25	15
Mechanics a	33⅓	60	10	30
Statistics a	33⅓	60	15	25
Modelling with Algorithms	33⅓	60	15	25
Numerical Methods	33⅓	60	25	15
Mechanics b	33⅓	60	10	30
Statistics b	33⅓	60	15	25

This gives the following mark weighting of each AO for each unit in the qualification.

	AO marks per unit		
	AO1	AO2	AO3
Core Pure	35–37 marks	13–17 marks	7–11 marks
Mechanics a	35–37 marks	5–8 marks	16–19 marks
Statistics a	35–37 marks	7–11 marks	13–17 marks
Modelling with Algorithms	35–37 marks	7–11 marks	13–17 marks
Numerical Methods	35–37 marks	13–17 marks	7–11 marks
Mechanics b	35–37 marks	5–8 marks	16–19 marks
Statistics b	35–37 marks	7–11 marks	13–17 marks

Note: There is a tolerance of ± 1 mark for AO1 with slightly more tolerance for AO2 and AO3.

Across all chosen papers combined in any given series, AO totals will fall within the following percentages for the qualification:

AO1 – 60% $\pm 2\%$

AO2 and AO3 – at least 10%

3c. Assessment availability

There will be one examination series available each year in May/June to **all** learners.

This specification will be certificated from the June 2018 examination series onwards.

All papers must be taken in the same examination series at the end of the course.

3d. Retaking the qualification

Learners can retake the qualification as many times as they wish. They must retake a complete valid

combination of examination papers for the qualification as detailed in section 2a.

3e. Assessment of extended response

The assessment materials for this qualification provide learners with the opportunity to demonstrate their ability to construct and develop a sustained

and coherent line of reasoning and marks for extended responses are integrated into the marking criteria.

3f. Synoptic assessment

Synoptic assessment allows learners to demonstrate the understanding they have acquired from the course as a whole and their ability to integrate and apply that understanding. This level of understanding is needed for successful use of the knowledge and skills from this course in future life, work and study.

Learners are required to know and understand all the content of AS Level Mathematics, and the assessment will reflect this when appropriate.

Learners are required to be able to apply the overarching themes from this specification, along with associated mathematical thinking and understanding.

In each optional examination paper learners are required to know and understand all the content of the Core Pure of this specification, and the assessment will reflect this when appropriate.

In each optional examination paper learners are required to draw together knowledge, skills and understanding from different parts of that content area.

In all the examination papers, learners will be required to integrate and apply their understanding in order to address problems which require both breadth and depth of understanding in order to reach a satisfactory solution.

Learners will be expected to reflect on and interpret solutions, drawing on their understanding of different aspects of the course.

3g. Calculating qualification results

A learner's overall qualification grade for AS Level in Further Mathematics B (MEI) will be calculated by adding together the marks from the Core Pure paper together with the two marks from the optional paper to give their total mark. Their total mark will then be compared to the qualification level grade boundaries that apply for the combination of papers taken by the learner and for the relevant exam series to determine the learner's overall qualification grade.

Where learners take more than the required number of papers, the combination of papers that result in the best **grade** will be used.

Note: this may NOT be the combination with the highest number of raw marks.

3

4 Admin: what you need to know

The information in this section is designed to give an overview of the processes involved in administering this qualification so that you can speak to your exams officer. All of the following processes require you to submit something to OCR by a specific deadline. More information about the processes and deadlines

involved at each stage of the assessment cycle can be found in the Administration area of the OCR website.

OCR's *Admin overview* is available on the OCR website at <http://www.ocr.org.uk/administration>.

4a. Pre-assessment

Estimated entries

Estimated entries are your best projection of the number of learners who will be entered for a qualification in a particular series. Estimated entries

should be submitted to OCR by the specified deadline. They are free and do not commit your centre in any way.

Final entries

Final entries provide OCR with detailed data for each learner, showing each assessment to be taken. It is essential that you use the correct entry code, considering the relevant entry rules.

Final entries must be submitted to OCR by the published deadlines or late entry fees will apply.

All learners taking AS Level in Further Mathematics B (MEI) must be entered for H635.

Entry code	Title	Code	Paper	Type
H635	Further Mathematics B (MEI)	Y410	Core Pure	Mandatory
		Y411	Mechanics a	Option
		Y412	Statistics a	Option
		Y413	Modelling with Algorithms	Option
		Y414	Numerical Methods	Option
		Y415	Mechanics b	Option
		Y416	Statistics b	Option
All assessments are by written examination.				

A Learner must be entered for the qualification entry code H635 and a combination of papers satisfying the following entry rules:

The mandatory paper Y410 must be entered, and at least two options (the combination of two optional paper that results in the best grade will count towards the award). **Note: this may NOT be the combination with the highest number of raw marks.**

4b. Special consideration

Special consideration is a post-assessment adjustment to marks or grades to reflect temporary injury, illness or other indisposition at the time the assessment was taken.

Detailed information about eligibility for special consideration can be found in the *JCQ publication A guide to the special consideration process*.

4c. External assessment arrangements

Regulations governing examination arrangements are contained in the *JCQ Instructions for conducting examinations*.

Head of centre annual declaration

The Head of Centre is required to provide a declaration to the JCQ as part of the annual NCN update, conducted in the autumn term, to confirm that the centre is meeting all of the requirements detailed in the specification. Any failure by a centre to

provide the Head of Centre Annual Declaration will result in your centre status being suspended and could lead to the withdrawal of our approval for you to operate as a centre.

Private Candidates

Private candidates may enter for OCR assessments.

A private candidate is someone who pursues a course of study independently but takes an examination or assessment at an approved examination centre. A private candidate may be a part-time student, someone taking a distance learning course, or someone being tutored privately. They must be based in the UK.

Private candidates need to contact OCR approved centres to establish whether they are prepared to host them as a private candidate. The centre may charge for this facility and OCR recommends that the arrangement is made early in the course.

Further guidance for private candidates may be found on the OCR website: <http://www.ocr.org.uk>

4d. Results and certificates

Grade Scale

AS Level qualifications are graded on the scale: A, B, C, D, E, where A is the highest. Learners who fail to reach the minimum standard for E will be Unclassified (U). Only subjects in which grades A to E are attained will be recorded on certificates.

Papers are graded on the scale a, b, c, d, e, where a is the highest. Learners who fail to reach the minimum standard for e will be unclassified (u). Individual paper results will not be recorded on certificates.

Results

Results are released to centres and learners for information and to allow any queries to be resolved before certificates are issued.

Centres will have access to the following results information for each learner:

- the grade for the qualification
- the raw mark for each paper
- the total weighted mark for the qualification.

The following supporting information will be available:

- raw mark grade boundaries for each paper
- weighted mark grade boundaries for the combinations of papers taken by their learners.

Until certificates are issued, results are deemed to be provisional and may be subject to amendment.

A learner's final results will be recorded on an OCR certificate. The qualification title will be shown on the certificate as 'OCR Level 3 Advanced Subsidiary GCE in Further Mathematics B (MEI)'.

4

4e. Post-results services

A number of post-results services are available:

- **Review of marking** – If you are not happy with the outcome of a learner's results, centres may request a review of marking. Full details of the post results services are provided on the OCR website.
- **Missing and incomplete results** – This service should be used if an individual subject result for a learner is missing, or the learner has been omitted entirely from the results supplied.
- **Access to scripts** – Centres can request access to marked scripts.

4f. Malpractice

Any breach of the regulations for the conduct of examinations and non-exam assessment may constitute malpractice (which includes maladministration) and must be reported to OCR as

soon as it is detected. Detailed information on malpractice can be found in the JCQ publication *Suspected Malpractice in Examinations and Assessments: Policies and Procedures*.

5 Appendices

5a. Overlap with other qualifications

This qualification overlaps with A Level Further Mathematics B (MEI) and with other specifications in A Level Further Mathematics and AS Level Further Mathematics.

The overlap with A Level Further Mathematics B (MEI) allows co-teachability with that qualification. The details are as follows:

AS Level Further Mathematics has same content as A Level Further Mathematics ...
Y410 Core Pure	Y420 Core Pure section (a)
Y411 Mechanics a	Y421 Mechanics Major section (a) <i>and</i> Y431 Mechanics Minor
Y412 Statistics a	Y422 Statistics Major section (a) <i>and</i> Y432 Statistics Minor
Y413 Modelling with Algorithms	Y433 Modelling with Algorithms
Y414 Numerical Methods	Y434 Numerical Methods
Y415 Mechanics b	Y421 Mechanics Major section (b)
Y416 Statistics b	Y422 Statistics Major section (b)

The following options are co-teachable with AS Mathematics

		Notes
Y410	Core Pure	From the non-AS content of A Level Mathematics, the use of radians and the use of the addition formulae for sin and cos are required.
Y411	Mechanics a	From the non-AS content of A Level Mathematics, some work on friction, the vector treatment of forces and the equilibrium are required. This content is clearly labelled in the specification for the unit.
Y412	Statistics a	
Y413	Modelling with Algorithms	
Y414	Numerical Methods	From the non-AS content of A level mathematics, the use of the Newton-Raphson method to solve equations is required.

Mechanics b and Statistics b are not designed to be co-teachable with AS Level Mathematics.

5b. Accessibility

Reasonable adjustments and access arrangements allow learners with special educational needs, disabilities or temporary injuries to access the assessment and show what they know and can do, without changing the demands of the assessment. Applications for these should be made before the examination series. Detailed information about eligibility for access arrangements can be found in the *JCQ Access Arrangements and Reasonable Adjustments*.

The AS Level qualification and subject criteria have been reviewed in order to identify any feature which could disadvantage learners who share a protected Characteristic as defined by the Equality Act 2010. All reasonable steps have been taken to minimise any such disadvantage.

5c. Mathematical notation

The tables below set out the notation that must be used by AS and A Level Mathematics and Further Mathematics specifications. Students will be expected

to understand this notation without need for further explanation.

1	Set Notation	
1.1	\in	is an element of
1.2	\notin	is not an element of
1.3	\subseteq	is a subset of
1.4	\subset	is a proper subset of
1.5	$\{x_1, x_2, \dots\}$	the set with elements x_1, x_2, \dots
1.6	$\{x: \dots\}$	the set of all x such that ...
1.7	$n(A)$	the number of elements in set A
1.8	\emptyset	the empty set
1.9	\mathcal{E}	the universal set
1.10	A'	the complement of the set A
1.11	\mathbb{N}	the set of natural numbers, $\{1, 2, 3, \dots\}$
1.12	\mathbb{Z}	the set of integers, $\{0, \pm 1, \pm 2, \pm 3, \dots\}$
1.13	\mathbb{Z}^+	the set of positive integers, $\{1, 2, 3, \dots\}$
1.14	\mathbb{Z}_0^+	the set of non-negative integers, $\{0, 1, 2, 3, \dots\}$
1.15	\mathbb{R}	the set of real numbers
1.16	\mathbb{Q}	the set of rational numbers, $\left\{\frac{p}{q} : p \in \mathbb{Z}, q \in \mathbb{Z}^+\right\}$
1.17	\cup	union
1.18	\cap	intersection
1.19	(x, y)	the ordered pair x, y
1.20	$[a, b]$	the closed interval $\{x \in \mathbb{R} : a \leq x \leq b\}$
1.21	$[a, b)$	the interval $\{x \in \mathbb{R} : a \leq x < b\}$
1.22	$(a, b]$	the interval $\{x \in \mathbb{R} : a < x \leq b\}$
1.23	(a, b)	the open interval $\{x \in \mathbb{R} : a < x < b\}$
1	Set Notation (Further Mathematics only)	
1.24	\mathbb{C}	the set of complex numbers

2	Miscellaneous Symbols	
2.1	=	is equal to
2.2	≠	is not equal to
2.3	≡	is identical to or is congruent to
2.4	≈	is approximately equal to
2.5	∞	infinity
2.6	∝	is proportional to
2.7	∴	therefore
2.8	∵	because
2.9	<	is less than
2.10	≤, ≤	is less than or equal to, is not greater than
2.11	>	is greater than
2.12	≥, ≥	is greater than or equal to, is not less than
2.13	$p \Rightarrow q$	p implies q (if p then q)
2.14	$p \Leftarrow q$	p is implied by q (if q then p)
2.15	$p \Leftrightarrow q$	p implies and is implied by q (p is equivalent to q)
2.16	a	first term for an arithmetic or geometric sequence
2.17	l	last term for an arithmetic sequence
2.18	d	common difference for an arithmetic sequence
2.19	r	common ratio for a geometric sequence
2.20	S_n	sum to n terms of a sequence
2.21	S_∞	sum to infinity of a sequence
3	Operations	
3.1	$a + b$	a plus b
3.2	$a - b$	a minus b
3.3	$a \times b, ab, a.b$	a multiplied by b
3.4	$a \div b, \frac{a}{b}$	a divided by b
3.5	$\sum_{i=1}^n a_i$	$a_1 + a_2 + \dots + a_n$
3.6	$\prod_{i=1}^n a_i$	$a_1 \times a_2 \times \dots \times a_n$
3.7	\sqrt{a}	the non-negative square root of a

3.8	$ a $	the modulus of a
3.9	$n!$	n factorial: $n! = n \times (n-1) \times \dots \times 2 \times 1$, $n \in \mathbb{N}$; $0! = 1$
3.10	$\binom{n}{r}, {}^n C_r, {}_n C_r$	the binomial coefficient $\frac{n!}{r!(n-r)!}$ for $n, r \in \mathbb{Z}_0^+$, $r \leq n$ or $\frac{n(n-1)\dots(n-r+1)}{r!}$ for $n \in \mathbb{Q}$, $r \in \mathbb{Z}_0^+$
4	Functions	
4.1	$f(x)$	the value of the function f at x
4.2	$f: x \mapsto y$	the function f maps the element x to the element y
4.3	f^{-1}	the inverse function of the function f
4.4	gf	the composite function of f and g which is defined by $gf(x) = g(f(x))$
4.5	$\lim_{x \rightarrow a} f(x)$	the limit of $f(x)$ as x tends to a
4.6	$\Delta x, \delta x$	an increment of x
4.7	$\frac{dy}{dx}$	the derivative of y with respect to x
4.8	$\frac{d^n y}{dx^n}$	the n th derivative of y with respect to x
4.9	$f'(x), f''(x), \dots, f^{(n)}(x)$	the first, second, ..., n th derivatives of $f(x)$ with respect to x
4.10	\dot{x}, \ddot{x}, \dots	the first, second, ... derivatives of x with respect to t
4.11	$\int y \, dx$	the indefinite integral of y with respect to x
4.12	$\int_a^b y \, dx$	the definite integral of y with respect to x between the limits $x = a$ and $x = b$
5	Exponential and Logarithmic Functions	
5.1	e	base of natural logarithms
5.2	$e^x, \exp x$	exponential function of x
5.3	$\log_a x$	logarithm to the base a of x
5.4	$\ln x, \log_e x$	natural logarithm of x
6	Trigonometric Functions	
6.1	$\left. \begin{array}{l} \sin, \cos, \tan \\ \operatorname{cosec}, \sec, \cot \end{array} \right\}$	the trigonometric functions
6.2	$\left. \begin{array}{l} \sin^{-1}, \cos^{-1}, \tan^{-1} \\ \arcsin, \arccos, \arctan \end{array} \right\}$	the inverse trigonometric functions

6.3	$^{\circ}$	degrees
6.4	rad	radians
7	Complex Numbers (Further Mathematics only)	
7.1	i, j	square root of -1
7.2	$x + iy$	complex number with real part x and imaginary part y
7.3	$r(\cos \theta + i \sin \theta)$	modulus argument form of a complex number with modulus r and argument θ
7.4	z	a complex number, $z = x + iy = r(\cos \theta + i \sin \theta)$
7.5	$\text{Re}(z)$	the real part of z , $\text{Re}(z) = x$
7.6	$\text{Im}(z)$	the imaginary part of z , $\text{Im}(z) = y$
7.7	$ z $	the modulus of z , $ z = \sqrt{x^2 + y^2}$
7.8	$\arg(z)$	the argument of z , $\arg(z) = \theta$, $-\pi < \theta \leq \pi$
7.9	z^*	the complex conjugate of z , $x - iy$
8	Matrices (Further Mathematics only)	
8.1	\mathbf{M}	a matrix \mathbf{M}
8.2	$\mathbf{0}$	zero matrix
8.3	\mathbf{I}	identity matrix
8.4	\mathbf{M}^{-1}	the inverse of the matrix \mathbf{M}
8.5	\mathbf{M}^T	the transpose of the matrix \mathbf{M}
8.6	$\Delta, \det \mathbf{M}$ or $ \mathbf{M} $	the determinant of the square matrix \mathbf{M}
8.7	$\mathbf{M}\mathbf{r}$	Image of column vector \mathbf{r} under the transformation associated with the matrix \mathbf{M}
9	Vectors	
9.1	$\mathbf{a}, \underline{a}, \underline{\underline{a}}$	the vector $\mathbf{a}, \underline{a}, \underline{\underline{a}}$; these alternatives apply throughout section 9
9.2	\overrightarrow{AB}	the vector represented in magnitude and direction by the directed line segment AB
9.3	$\hat{\mathbf{a}}$	a unit vector in the direction of \mathbf{a}
9.4	$\mathbf{i}, \mathbf{j}, \mathbf{k}$	unit vectors in the directions of the cartesian coordinate axes
9.5	$ \mathbf{a} , a$	the magnitude of \mathbf{a}
9.6	$ \overrightarrow{AB} , AB$	the magnitude of \overrightarrow{AB}
9.7	$\begin{pmatrix} a \\ b \end{pmatrix}, a\mathbf{i} + b\mathbf{j}$	column vector and corresponding unit vector notation

9.8	\mathbf{r}	position vector
9.9	\mathbf{s}	displacement vector
9.10	\mathbf{v}	velocity vector
9.11	\mathbf{a}	acceleration vector
9	Vectors (Further Mathematics only)	
9.12	$\mathbf{a} \cdot \mathbf{b}$	the scalar product of \mathbf{a} and \mathbf{b}
10	Differential Equations (Further Mathematics only)	
10.1	ω	angular speed
11	Probability and Statistics	
11.1	$A, B, C, \text{ etc.}$	events
11.2	$A \cup B$	union of the events A and B
11.3	$A \cap B$	intersection of the events A and B
11.4	$P(A)$	probability of the event A
11.5	A'	complement of the event A
11.6	$P(A B)$	probability of the event A conditional on the event B
11.7	$X, Y, R, \text{ etc.}$	random variables
11.8	$x, y, r, \text{ etc.}$	values of the random variables X, Y, R etc.
11.9	x_1, x_2, \dots	observations
11.10	f_1, f_2, \dots	frequencies with which the observations x_1, x_2, \dots occur
11.11	$p(x), P(X=x)$	probability function of the discrete random variable X
11.12	p_1, p_2, \dots	probabilities of the values x_1, x_2, \dots of the discrete random variable X
11.13	$E(X)$	expectation of the random variable X
11.14	$\text{Var}(X)$	variance of the random variable X
11.15	\sim	has the distribution
11.16	$B(n, p)$	binomial distribution with parameters n and p , where n is the number of trials and p is the probability of success in a trial
11.17	q	$q = 1 - p$ for binomial distribution
11.18	$N(\mu, \sigma^2)$	Normal distribution with mean μ and variance σ^2
11.19	$Z \sim N(0, 1)$	standard Normal distribution
11.20	ϕ	probability density function of the standardised Normal variable with distribution $N(0, 1)$
11.21	Φ	corresponding cumulative distribution function
11.22	μ	population mean

11.23	σ^2	population variance
11.24	σ	population standard deviation
11.25	\bar{x}	sample mean
11.26	s^2	sample variance
11.27	s	sample standard deviation
11.28	H_0	Null hypothesis
11.29	H_1	Alternative hypothesis
11.30	r	product moment correlation coefficient for a sample
11.31	ρ	product moment correlation coefficient for a population
12	Mechanics	
12.1	kg	kilograms
12.2	m	metres
12.3	km	kilometres
12.4	m/s, m s ⁻¹	metres per second (velocity)
12.5	m/s ² , m s ⁻²	metres per second per second (acceleration)
12.6	F	Force or resultant force
12.7	N	Newton
12.8	N m	Newton metre (moment of a force)
12.9	t	time
12.10	s	displacement
12.11	u	initial velocity
12.12	v	velocity or final velocity
12.13	a	acceleration
12.14	g	acceleration due to gravity
12.15	μ	coefficient of friction

5d. Mathematical formulae, identities and statistical tables

Learners must be able to use the following formulae and identities for AS and A Level Further Mathematics, without these formulae and identities being provided, either in these forms or in equivalent forms. These formulae and identities may only be provided where they are the starting point for a proof or as a result to be proved.

Pure Mathematics

Quadratic Equations

$$ax^2 + bx + c = 0 \text{ has roots } \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

Laws of Indices

$$a^x a^y \equiv a^{x+y}$$

$$a^x \div a^y \equiv a^{x-y}$$

$$(a^x)^y \equiv a^{xy}$$

Laws of Logarithms

$$x = a^n \Leftrightarrow n = \log_a x \text{ for } a > 0 \text{ and } x > 0$$

$$\log_a x + \log_a y \equiv \log_a (xy)$$

$$\log_a x - \log_a y \equiv \log_a \left(\frac{x}{y} \right)$$

$$k \log_a x \equiv \log_a (x^k)$$

Coordinate Geometry

A straight line graph, gradient m passing through (x_1, y_1) has equation

$$y - y_1 = m(x - x_1)$$

Straight lines with gradients m_1 and m_2 are perpendicular when $m_1 m_2 = -1$

Sequences

General term of an arithmetic progression:

$$u_n = a + (n - 1)d$$

General term of a geometric progression:

$$u_n = ar^{n-1}$$

Trigonometry

In the triangle ABC

$$\text{Sine rule: } \frac{a}{\sin A} = \frac{b}{\sin B} = \frac{c}{\sin C}$$

$$\text{Cosine rule: } a^2 = b^2 + c^2 - 2bc \cos A$$

$$\text{Area} = \frac{1}{2} ab \sin C$$

$$\cos^2 A + \sin^2 A \equiv 1$$

$$\sec^2 A \equiv 1 + \tan^2 A$$

$$\operatorname{cosec}^2 A \equiv 1 + \cot^2 A$$

$$\sin 2A \equiv 2 \sin A \cos A$$

$$\cos 2A \equiv \cos^2 A - \sin^2 A$$

$$\tan 2A \equiv \frac{2 \tan A}{1 - \tan^2 A}$$

Mensuration

Circumference and Area of circle, radius r and diameter d :

$$C = 2\pi r = \pi d \quad A = \pi r^2$$

Pythagoras' Theorem: In any right-angled triangle where a , b and c are the lengths of the sides and c is the hypotenuse:

$$c^2 = a^2 + b^2$$

Area of a trapezium = $\frac{1}{2}(a + b)h$, where a and b are the lengths of the parallel sides and h is their perpendicular separation.

Volume of a prism = area of cross section \times length

For a circle of radius r , where an angle at the centre of θ radians subtends an arc of length l and encloses an associated sector of area a :

$$l = r\theta \quad a = \frac{1}{2}r^2\theta$$

Complex Numbers

For two complex numbers $z_1 = r_1 e^{i\theta_1}$ and $z_2 = r_2 e^{i\theta_2}$:

$$z_1 z_2 = r_1 r_2 e^{i(\theta_1 + \theta_2)}$$

$$\frac{z_1}{z_2} = \frac{r_1}{r_2} e^{i(\theta_1 - \theta_2)}$$

Loci in the Argand diagram:

$|z - a| = r$ is a circle radius r centred at a

$\arg(z - a) = \theta$ is a half line drawn from a at angle θ to a line parallel to the positive real axis

Exponential Form:

$$e^{i\theta} = \cos \theta + i \sin \theta$$

Matrices

For a 2 by 2 matrix $\begin{pmatrix} a & b \\ c & d \end{pmatrix}$ the determinant $\Delta = \begin{vmatrix} a & b \\ c & d \end{vmatrix} = ad - bc$

the inverse is $\frac{1}{\Delta} \begin{pmatrix} d & -b \\ -c & a \end{pmatrix}$

The transformation represented by matrix \mathbf{AB} is the transformation represented by matrix \mathbf{B} followed by the transformation represented by matrix \mathbf{A} .

For matrices \mathbf{A} , \mathbf{B} :

$$(\mathbf{AB})^{-1} = \mathbf{B}^{-1}\mathbf{A}^{-1}$$

Algebra

$$\sum_{r=1}^n r = \frac{1}{2}n(n+1)$$

For $ax^2 + bx + c = 0$ with roots α and β :

$$\alpha + \beta = \frac{-b}{a} \quad \alpha\beta = \frac{c}{a}$$

For $ax^3 + bx^2 + cx + d = 0$ with roots α , β and γ :

$$\sum \alpha = \frac{-b}{a} \quad \sum \alpha\beta = \frac{c}{a} \quad \alpha\beta\gamma = \frac{-d}{a}$$

Hyperbolic Functions

$$\cosh x \equiv \frac{1}{2}(e^x + e^{-x})$$

$$\sinh x \equiv \frac{1}{2}(e^x - e^{-x})$$

$$\tanh x \equiv \frac{\sinh x}{\cosh x}$$

Calculus and Differential EquationsDifferentiation

Function	Derivative
x^n	nx^{n-1}
$\sin kx$	$k \cos kx$
$\cos kx$	$-k \sin kx$
$\sinh kx$	$k \cosh kx$
$\cosh kx$	$k \sinh kx$
e^{kx}	ke^{kx}
$\ln x$	$\frac{1}{x}$
$f(x) + g(x)$	$f'(x) + g'(x)$
$f(x)g(x)$	$f'(x)g(x) + f(x)g'(x)$
$f(g(x))$	$f'(g(x))g'(x)$

Integration

Function	Integral
x^n	$\frac{1}{n+1}x^{n+1} + c, n \neq -1$
$\cos kx$	$\frac{1}{k} \sin kx + c$
$\sin kx$	$-\frac{1}{k} \cos kx + c$
$\cosh kx$	$\frac{1}{k} \sinh kx + c$
$\sinh kx$	$\frac{1}{k} \cosh kx + c$

$$\begin{array}{ll} e^{kx} & \frac{1}{k}e^{kx} + c \\ \frac{1}{x} & \ln|x| + c, x \neq 0 \\ f'(x) + g'(x) & f(x) + g(x) + c \\ f'(g(x))g'(x) & f(g(x)) + c \end{array}$$

$$\text{Area under a curve} = \int_a^b y \, dx (y \geq 0)$$

Volumes of revolution about the x and y axes:

$$V_x = \pi \int_a^b y^2 \, dx \qquad V_y = \pi \int_c^d x^2 \, dy$$

Simple Harmonic Motion:

$$\ddot{x} = -\omega^2 x$$

Vectors

$$|\mathbf{x}\mathbf{i} + \mathbf{y}\mathbf{j} + \mathbf{z}\mathbf{k}| = \sqrt{(x^2 + y^2 + z^2)}$$

Scalar product of two vectors $\mathbf{a} = \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix}$ and $\mathbf{b} = \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix}$ is

$$\begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix} \cdot \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix} = a_1 b_1 + a_2 b_2 + a_3 b_3 = |\mathbf{a}| |\mathbf{b}| \cos \theta$$

where θ is the acute angle between the vectors \mathbf{a} and \mathbf{b}

The equation of the line through the point with position vector \mathbf{a} parallel to vector \mathbf{b} is:

$$\mathbf{r} = \mathbf{a} + t\mathbf{b}$$

The equation of the plane containing the point with position vector \mathbf{a} and perpendicular to vector \mathbf{n} is:

$$(\mathbf{r} - \mathbf{a}) \cdot \mathbf{n} = 0$$

Mechanics

Forces and Equilibrium

$$\text{Weight} = \text{mass} \times g$$

$$\text{Friction: } F \leq \mu R$$

$$\text{Newton's second law in the form: } F = ma$$

Kinematics

For motion in a straight line with variable acceleration:

$$v = \frac{dr}{dt} \quad a = \frac{dv}{dt} = \frac{d^2r}{dt^2}$$

$$r = \int v dt \quad v = \int a dt$$

Statistics

The mean of a set of data: $\bar{x} = \frac{\sum x}{n} = \frac{\sum fx}{\sum f}$

The standard Normal variable: $Z = \frac{X - \mu}{\sigma}$ where $X \sim N(\mu, \sigma^2)$

Learners will be provided with the following formulae and statistical tables in each examination for AS Level Further Mathematics B (MEI). Please note that the same formula booklet will be used for AS and A Level Further Mathematics B (MEI).

Contents

A Level Mathematics
Core Pure
Mechanics
Further Pure with Technology
Extra Pure
Numerical Methods
Statistics
Statistical tables

A Level Mathematics**Arithmetic series**

$$S_n = \frac{1}{2}n(a+l) = \frac{1}{2}n\{2a+(n-1)d\}$$

Geometric series

$$S_n = \frac{a(1-r^n)}{1-r}$$

$$S_\infty = \frac{a}{1-r} \text{ for } |r| < 1$$

Binomial series

$$(a+b)^n = a^n + {}^n C_1 a^{n-1} b + {}^n C_2 a^{n-2} b^2 + \dots + {}^n C_r a^{n-r} b^r + \dots + b^n \quad (n \in \mathbb{N}),$$

$$\text{where } {}^n C_r = {}_n C_r = \binom{n}{r} = \frac{n!}{r!(n-r)!}$$

$$(1+x)^n = 1 + nx + \frac{n(n-1)}{2!} x^2 + \dots + \frac{n(n-1)\dots(n-r+1)}{r!} x^r + \dots \quad (|x| < 1, n \in \mathbb{R})$$

Differentiation

$f(x)$	$f'(x)$
$\tan kx$	$k \sec^2 kx$
$\sec x$	$\sec x \tan x$
$\cot x$	$-\operatorname{cosec}^2 x$
$\operatorname{cosec} x$	$-\operatorname{cosec} x \cot x$

$$\text{Quotient Rule } y = \frac{u}{v}, \quad \frac{dy}{dx} = \frac{v \frac{du}{dx} - u \frac{dv}{dx}}{v^2}$$

Differentiation from first principles

$$f'(x) = \lim_{h \rightarrow 0} \frac{f(x+h) - f(x)}{h}$$

Integration

$$\int \frac{f'(x)}{f(x)} dx = \ln|f(x)| + c$$

$$\int f'(x)(f(x))^n dx = \frac{1}{n+1} (f(x))^{n+1} + c$$

$$\text{Integration by parts } \int u \frac{dv}{dx} dx = uv - \int v \frac{du}{dx} dx$$

Small Angle Approximations

$$\sin \theta \approx \theta, \quad \cos \theta \approx 1 - \frac{1}{2}\theta^2, \quad \tan \theta \approx \theta \quad \text{where } \theta \text{ is measured in radians}$$

Trigonometric identities

$$\sin(A \pm B) = \sin A \cos B \pm \cos A \sin B$$

$$\cos(A \pm B) = \cos A \cos B \mp \sin A \sin B$$

$$\tan(A \pm B) = \frac{\tan A \pm \tan B}{1 \mp \tan A \tan B} \quad (A \pm B \neq (k + \frac{1}{2})\pi)$$

Numerical methods

Trapezium rule: $\int_a^b y \, dx \approx \frac{1}{2}h \{(y_0 + y_n) + 2(y_1 + y_2 + \dots + y_{n-1})\}$, where $h = \frac{b-a}{n}$

The Newton-Raphson iteration for solving $f(x) = 0$: $x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}$

Probability

$$P(A \cup B) = P(A) + P(B) - P(A \cap B)$$

$$P(A \cap B) = P(A)P(B|A) = P(B)P(A|B) \text{ or } P(A|B) = \frac{P(A \cap B)}{P(B)}$$

Sample Variance

$$s^2 = \frac{1}{n-1} S_{xx} \text{ where } S_{xx} = \sum (x_i - \bar{x})^2 = \sum x_i^2 - \frac{(\sum x_i)^2}{n} = \sum x_i^2 - n\bar{x}^2$$

Standard deviation, $s = \sqrt{\text{variance}}$

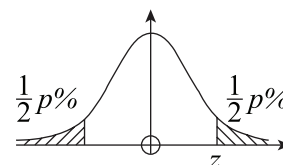
The Binomial Distribution

If $X \sim B(n, p)$ then $P(X = r) = {}^n C_r p^r q^{n-r}$ where $q = 1 - p$

Mean of X is np

Hypothesis test for the mean of a Normal distribution

If $X \sim N(\mu, \sigma^2)$ then $\bar{X} \sim N\left(\mu, \frac{\sigma^2}{n}\right)$ and $\frac{\bar{X} - \mu}{\sigma/\sqrt{n}} \sim N(0, 1)$

**Percentage points of the normal distribution**

p	10	5	2	1
z	1.645	1.960	2.326	2.576

Kinematics

Motion in a straight line

$$v = u + at$$

$$s = ut + \frac{1}{2}at^2$$

$$s = \frac{1}{2}(u + v)t$$

$$v^2 = u^2 + 2as$$

$$s = vt - \frac{1}{2}at^2$$

Motion in two dimensions

$$\mathbf{v} = \mathbf{u} + \mathbf{a}t$$

$$\mathbf{s} = \mathbf{u}t + \frac{1}{2}\mathbf{a}t^2$$

$$\mathbf{s} = \frac{1}{2}(\mathbf{u} + \mathbf{v})t$$

-

$$\mathbf{s} = \mathbf{v}t - \frac{1}{2}\mathbf{a}t^2$$

Core Pure

Complex Numbers

De Moivre's theorem:

$$\{r(\cos \theta + i \sin \theta)\}^n = r^n(\cos n\theta + i \sin n\theta)$$

Roots of unity:

$$\text{The roots of } z^n = 1 \text{ are given by } z = \exp\left(\frac{2\pi k}{n}i\right) \text{ for } k = 0, 1, 2, \dots, n-1$$

Vectors and 3-D geometry

Cartesian equation of a plane is

$$n_1x + n_2y + n_3z + d = 0$$

Cartesian equation of a line in 3-D is

$$\frac{x - a_1}{d_1} = \frac{y - a_2}{d_2} = \frac{z - a_3}{d_3}$$

$$\text{Vector product } \mathbf{a} \times \mathbf{b} = \begin{pmatrix} a_2b_3 - a_3b_2 \\ a_3b_1 - a_1b_3 \\ a_1b_2 - a_2b_1 \end{pmatrix}$$

Distance between skew lines is $\left| \frac{\mathbf{d}_1 \times \mathbf{d}_2}{|\mathbf{d}_1 \times \mathbf{d}_2|} \cdot (\mathbf{a}_1 - \mathbf{a}_2) \right|$ where \mathbf{a}_1 is the position vector of a point on the first line and \mathbf{d}_1 is parallel to the first line, similarly for the second line.

Distance between point (x_1, y_1) and line $ax + by + c = 0$ is $\frac{|ax_1 + by_1 + c|}{\sqrt{a^2 + b^2}}$

Distance between point (x_1, y_1, z_1) and plane $n_1x + n_2y + n_3z + d = 0$ is $\frac{|n_1x_1 + n_2y_1 + n_3z_1 + d|}{\sqrt{n_1^2 + n_2^2 + n_3^2}}$

Hyperbolic functions

$$\cosh^2 x - \sinh^2 x = 1$$

$$\operatorname{arsinh} x = \ln[x + \sqrt{(x^2 + 1)}]$$

$$\operatorname{arcosh} x = \ln[x + \sqrt{(x^2 - 1)}], x \geq 1$$

$$\operatorname{artanh} x = \frac{1}{2} \ln\left(\frac{1+x}{1-x}\right), -1 < x < 1$$

Calculus

$f(x)$	$f'(x)$
$\arcsin x$	$\frac{1}{\sqrt{1-x^2}}$
$\arccos x$	$-\frac{1}{\sqrt{1-x^2}}$
$\arctan x$	$\frac{1}{1+x^2}$

$f(x)$	$\int f(x) dx$
$\frac{1}{\sqrt{a^2-x^2}}$	$\arcsin\left(\frac{x}{a}\right) + c \quad (x < a)$
$\frac{1}{a^2+x^2}$	$\frac{1}{a} \arctan\left(\frac{x}{a}\right) + c$
$\frac{1}{\sqrt{a^2+x^2}}$	$\operatorname{arsinh}\left(\frac{x}{a}\right) + c$ or $\ln(x + \sqrt{x^2+a^2}) + c$
$\frac{1}{\sqrt{x^2-a^2}}$	$\operatorname{arcosh}\left(\frac{x}{a}\right) + c$ or $\ln(x + \sqrt{x^2-a^2}) + c \quad (x > a)$

The mean value of $f(x)$ on the interval $[a, b]$ is $\frac{1}{b-a} \int_a^b f(x) dx$

Area of sector enclosed by polar curve is $\frac{1}{2} \int r^2 d\theta$

Series

$$\sum_{r=1}^n r^2 = \frac{1}{6} n(n+1)(2n+1), \quad \sum_{r=1}^n r^3 = \frac{1}{4} n^2(n+1)^2$$

$$f(x) = f(0) + f'(0)x + \frac{f''(0)}{2!}x^2 + \dots + \frac{f^{(r)}(0)}{r!}x^r + \dots$$

$$e^x = \exp(x) = 1 + x + \frac{x^2}{2!} + \dots + \frac{x^r}{r!} + \dots \text{ for all } x$$

$$\ln(1+x) = x - \frac{x^2}{2} + \frac{x^3}{3} - \dots + (-1)^{r+1} \frac{x^r}{r} + \dots \quad (-1 < x \leq 1)$$

$$\sin x = x - \frac{x^3}{3!} + \frac{x^5}{5!} - \dots + (-1)^r \frac{x^{2r+1}}{(2r+1)!} + \dots \text{ for all } x$$

$$\cos x = 1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \dots + (-1)^r \frac{x^{2r}}{(2r)!} + \dots \text{ for all } x$$

$$(1+x)^n = 1 + nx + \frac{n(n-1)}{2!}x^2 + \dots + \frac{n(n-1)\dots(n-r+1)}{r!}x^r + \dots \quad (|x| < 1, n \in \mathbb{R})$$

Mechanics

Motion in a circle

For motion in a circle,

tangential velocity is $v = r\dot{\theta}$

radial acceleration is $\frac{v^2}{r}$ or $r\dot{\theta}^2$ towards the centre

tangential acceleration is $r\ddot{\theta}$

Further Pure with Technology

Numerical solution of differential equations

For $\frac{dy}{dx} = f(x, y)$:

Euler's method: $x_{n+1} = x + h, y_{n+1} = y_n + hf(x_n, y_n)$

Modified Euler method (A Runge-Kutta method of order 2):

$$k_1 = hf(x_n, y_n)$$

$$k_2 = hf(x_n + h, y_n + k_1)$$

$$x_{n+1} = x_n + h, y_{n+1} = y_n + \frac{1}{2}(k_1 + k_2)$$

Runge-Kutta method of order 4:

$$k_1 = hf(x_n, y_n)$$

$$k_2 = hf\left(x_n + \frac{h}{2}, y_n + \frac{k_1}{2}\right)$$

$$k_3 = hf\left(x_n + \frac{h}{2}, y_n + \frac{k_2}{2}\right)$$

$$k_4 = hf(x_n + h, y_n + k_3)$$

$$y_{n+1} = y_n + \frac{1}{6}(k_1 + 2k_2 + 2k_3 + k_4)$$

Gradient of tangent to a polar curve

For a curve $r = f(\theta)$, $\frac{dy}{dx} = \frac{\frac{dr}{d\theta} \sin \theta + r \cos \theta}{\frac{dr}{d\theta} \cos \theta - r \sin \theta}$

Extra Pure

Multivariable calculus

$$\nabla g = \mathbf{grad} g = \begin{pmatrix} \frac{\partial g}{\partial x} \\ \frac{\partial g}{\partial y} \\ \frac{\partial g}{\partial z} \end{pmatrix}. \text{ If } g(x, y, z) \text{ can be written as } z = f(x, y) \text{ then } \mathbf{grad} g = \begin{pmatrix} \frac{\partial f}{\partial x} \\ \frac{\partial f}{\partial y} \\ -1 \end{pmatrix}$$

Numerical Methods

Solution of equations

The Newton-Raphson iteration for solving $f(x) = 0$: $x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}$

For the iteration $x_{n+1} = g(x_n)$ the relaxed iteration is $x_{n+1} = (1 - \lambda)x_n + \lambda g(x_n)$.

Numerical integration

To estimate $\int_a^b f(x) dx$:

The midpoint rule:

$$M_n = h(y_{\frac{1}{2}} + y_{\frac{3}{2}} + \dots + y_{n-\frac{3}{2}} + y_{n-\frac{1}{2}}) \quad \text{where } h = \frac{b-a}{n}$$

The trapezium rule:

$$T_n = \frac{1}{2}h\{(y_0 + y_n) + 2(y_1 + y_2 + \dots + y_{n-1})\} \quad \text{where } h = \frac{b-a}{n}$$

Simpson's rule

$$S_{2n} = \frac{1}{3}h\{(y_0 + y_{2n}) + 4(y_1 + y_3 + \dots + y_{2n-1}) + 2(y_2 + y_4 + \dots + y_{2n-2})\}$$

where $h = \frac{b-a}{2n}$.

These are related as follows:

$$T_{2n} = \frac{1}{2}(M_n + T_n)$$

$$S_{2n} = \frac{1}{3}(2M_n + T_n) = \frac{1}{3}(4T_{2n} - T_n)$$

Interpolation

Newton's forward difference interpolation formula:

$$f(x) = f(x_0) + \frac{(x-x_0)}{h}\Delta f(x_0) + \frac{(x-x_0)(x-x_1)}{2!h^2}\Delta^2 f(x_0) + \dots$$

Lagrange's polynomial:

$$P_n(x) = \sum L_r(x) f(x_r) \quad \text{where } L_r(x) = \prod_{\substack{i=0 \\ i \neq r}}^n \frac{x-x_i}{x_r-x_i}$$

Statistics

Discrete distributions

X is a random variable taking values x_i in a discrete distribution with $P(X = x_i) = p_i$

$$\text{Expectation: } \mu = E(X) = \sum x_i p_i$$

$$\text{Variance: } \sigma^2 = \text{Var}(X) = \sum (x_i - \mu)^2 p_i = \sum x_i^2 p_i - \mu^2$$

	Probability	$E(X)$	$\text{Var}(X)$
Uniform distribution over $1, 2, \dots, n$	$P(X = r) = \frac{1}{n}$	$\frac{n+1}{2}$	$\frac{1}{12}(n^2 - 1)$
Geometric distribution	$P(X = r) = q^{r-1}p$ $q = 1 - p$	$\frac{1}{p}$	$\frac{1-p}{p^2}$
Poisson distribution	$P(X = r) = e^{-\lambda} \frac{\lambda^r}{r!}$		

5

Correlation and regression

For a sample of n pairs of observations (x_i, y_i)

$$S_{xx} = \sum x_i^2 - \frac{(\sum x_i)^2}{n}, S_{yy} = \sum y_i^2 - \frac{(\sum y_i)^2}{n}, S_{xy} = \sum x_i y_i - \frac{\sum x_i \sum y_i}{n}$$

$$\text{product moment correlation coefficient: } r = \frac{S_{xy}}{\sqrt{S_{xx} S_{yy}}} = \frac{\sum x_i y_i - \frac{\sum x_i \sum y_i}{n}}{\sqrt{\left[\left(\sum x_i^2 - \frac{(\sum x_i)^2}{n} \right) \left(\sum y_i^2 - \frac{(\sum y_i)^2}{n} \right) \right]}}$$

$$\text{least squares regression line of } y \text{ on } x \text{ is } y - \bar{y} = b(x - \bar{x}) \text{ where } b = \frac{S_{xy}}{S_{xx}} = \frac{\sum x_i y_i - \frac{\sum x_i \sum y_i}{n}}{\sum x_i^2 - \frac{(\sum x_i)^2}{n}}$$

$$\text{least squares regression line of } x \text{ on } y \text{ is } x - \bar{x} = b'(y - \bar{y}) \text{ where } b' = \frac{S_{xy}}{S_{yy}} = \frac{\sum x_i y_i - \frac{\sum x_i \sum y_i}{n}}{\sum y_i^2 - \frac{(\sum y_i)^2}{n}}$$

Spearman's coefficient of rank correlation:

$$r_s = 1 - \frac{6 \sum d_i^2}{n(n^2 - 1)}$$

Confidence intervals

To calculate a confidence interval for a mean or difference in mean in different circumstances, use the given distribution to calculate the critical value, k .

To estimate...	Confidence interval	Distribution
a mean	$\bar{x} \pm k \frac{\sigma}{\sqrt{n}}$	$N(0, 1)$
a mean	$\bar{x} \pm k \frac{s}{\sqrt{n}}$	t_{n-1}
difference in mean of paired populations	treat differences as a single distribution	

Hypothesis tests

Description	Test statistic	Distribution
Pearson's product moment correlation test	$r = \frac{S_{xy}}{\sqrt{S_{xx}S_{yy}}}$ $= \frac{\sum x_i y_i - \frac{\sum x_i \sum y_i}{n}}{\sqrt{\left[\left(\sum x_i^2 - \frac{(\sum x_i)^2}{n} \right) \left(\sum y_i^2 - \frac{(\sum y_i)^2}{n} \right) \right]}}$	
Spearman's rank correlation test	$r_s = 1 - \frac{6 \sum d_i^2}{n(n^2 - 1)}$	
χ^2 test	$\sum \frac{(f_o - f_e)^2}{f_e}$	χ^2_v
Normal test for a mean	$\frac{\bar{x} - \mu}{\left(\frac{\sigma}{\sqrt{n}} \right)}$	$N(0, 1)$
t -test for a mean	$\frac{\bar{x} - \mu}{\left(\frac{s}{\sqrt{n}} \right)}$	t_{n-1}
Wilcoxon single sample test	A statistic T is calculated from the ranked data	

Continuous distributions

X is a continuous random variable with probability density function (pdf) $f(x)$

Expectation: $\mu = E(X) = \int xf(x) dx$

Variance: $\sigma^2 = \text{Var}(X) = \int (x - \mu)^2 f(x) dx = \int x^2 f(x) dx - \mu^2$

Cumulative distribution function $F(x) = P(X \leq x) = \int_{-\infty}^x f(t) dt$

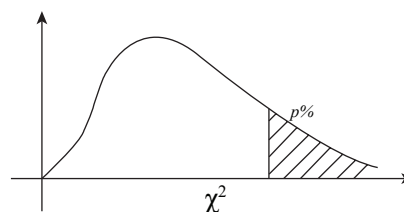
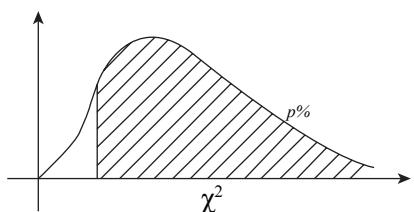
	$E(X)$	$\text{Var}(X)$
Continuous uniform distribution over $[a, b]$	$\frac{a+b}{2}$	$\frac{1}{12}(b-a)^2$

Critical values for the product moment correlation coefficient, r

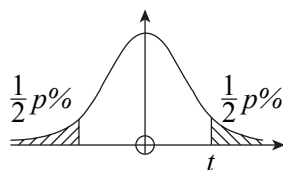
n	1-Tail Test				n	1-Tail Test			
	5%	2½%	1%	½%		5%	2½%	1%	½%
	10%	5%	2%	1%		10%	5%	2%	1%
1	–	–	–	–	31	0.3009	0.3550	0.4158	0.4556
2	–	–	–	–	32	0.2960	0.3494	0.4093	0.4487
3	0.9877	0.9969	0.9995	0.9999	33	0.2913	0.3440	0.4032	0.4421
4	0.9000	0.9500	0.9800	0.9900	34	0.2869	0.3388	0.3972	0.4357
5	0.8054	0.8783	0.9343	0.9587	35	0.2826	0.3338	0.3916	0.4296
6	0.7293	0.8114	0.8822	0.9172	36	0.2785	0.3291	0.3862	0.4238
7	0.6694	0.7545	0.8329	0.8745	37	0.2746	0.3246	0.3810	0.4182
8	0.6215	0.7067	0.7887	0.8343	38	0.2709	0.3202	0.3760	0.4128
9	0.5822	0.6664	0.7498	0.7977	39	0.2673	0.3160	0.3712	0.4076
10	0.5494	0.6319	0.7155	0.7646	40	0.2638	0.3120	0.3665	0.4026
11	0.5214	0.6021	0.6851	0.7348	41	0.2605	0.3081	0.3621	0.3978
12	0.4973	0.5760	0.6581	0.7079	42	0.2573	0.3044	0.3578	0.3932
13	0.4762	0.5529	0.6339	0.6835	43	0.2542	0.3008	0.3536	0.3887
14	0.4575	0.5324	0.6120	0.6614	44	0.2512	0.2973	0.3496	0.3843
15	0.4409	0.5140	0.5923	0.6411	45	0.2483	0.2940	0.3457	0.3801
16	0.4259	0.4973	0.5742	0.6226	46	0.2455	0.2907	0.3420	0.3761
17	0.4124	0.4821	0.5577	0.6055	47	0.2429	0.2876	0.3384	0.3721
18	0.4000	0.4683	0.5425	0.5897	48	0.2403	0.2845	0.3348	0.3683
19	0.3887	0.4555	0.5285	0.5751	49	0.2377	0.2816	0.3314	0.3646
20	0.3783	0.4438	0.5155	0.5614	50	0.2353	0.2787	0.3281	0.3610
21	0.3687	0.4329	0.5034	0.5487	51	0.2329	0.2759	0.3249	0.3575
22	0.3598	0.4227	0.4921	0.5368	52	0.2306	0.2732	0.3218	0.3542
23	0.3515	0.4132	0.4815	0.5256	53	0.2284	0.2706	0.3188	0.3509
24	0.3438	0.4044	0.4716	0.5151	54	0.2262	0.2681	0.3158	0.3477
25	0.3365	0.3961	0.4622	0.5052	55	0.2241	0.2656	0.3129	0.3445
26	0.3297	0.3882	0.4534	0.4958	56	0.2221	0.2632	0.3102	0.3415
27	0.3233	0.3809	0.4451	0.4869	57	0.2201	0.2609	0.3074	0.3385
28	0.3172	0.3739	0.4372	0.4785	58	0.2181	0.2586	0.3048	0.3357
29	0.3115	0.3673	0.4297	0.4705	59	0.2162	0.2564	0.3022	0.3328
30	0.3061	0.3610	0.4226	0.4629	60	0.2144	0.2542	0.2997	0.3301

Critical values for Spearman's rank correlation coefficient, r_s

n	1-Tail Test				n	1-Tail Test			
	5%	2½%	1%	½%		5%	2½%	1%	½%
	10%	5%	2%	1%		10%	5%	2%	1%
1	–	–	–	–	31	0.3012	0.3560	0.4185	0.4593
2	–	–	–	–	32	0.2962	0.3504	0.4117	0.4523
3	–	–	–	–	33	0.2914	0.3449	0.4054	0.4455
4	1.0000	–	–	–	34	0.2871	0.3396	0.3995	0.4390
5	0.9000	1.0000	1.0000	–	35	0.2829	0.3347	0.3936	0.4328
6	0.8286	0.8857	0.9429	1.0000	36	0.2788	0.3300	0.3882	0.4268
7	0.7143	0.7857	0.8929	0.9286	37	0.2748	0.3253	0.3829	0.4211
8	0.6429	0.7381	0.8333	0.8810	38	0.2710	0.3209	0.3778	0.4155
9	0.6000	0.7000	0.7833	0.8333	39	0.2674	0.3168	0.3729	0.4103
10	0.5636	0.6485	0.7455	0.7939	40	0.2640	0.3128	0.3681	0.4051
11	0.5364	0.6182	0.7091	0.7545	41	0.2606	0.3087	0.3636	0.4002
12	0.5035	0.5874	0.6783	0.7273	42	0.2574	0.3051	0.3594	0.3955
13	0.4835	0.5604	0.6484	0.7033	43	0.2543	0.3014	0.3550	0.3908
14	0.4637	0.5385	0.6264	0.6791	44	0.2513	0.2978	0.3511	0.3865
15	0.4464	0.5214	0.6036	0.6536	45	0.2484	0.2945	0.3470	0.3822
16	0.4294	0.5029	0.5824	0.6353	46	0.2456	0.2913	0.3433	0.3781
17	0.4142	0.4877	0.5662	0.6176	47	0.2429	0.2880	0.3396	0.3741
18	0.4014	0.4716	0.5501	0.5996	48	0.2403	0.2850	0.3361	0.3702
19	0.3912	0.4596	0.5351	0.5842	49	0.2378	0.2820	0.3326	0.3664
20	0.3805	0.4466	0.5218	0.5699	50	0.2353	0.2791	0.3293	0.3628
21	0.3701	0.4364	0.5091	0.5558	51	0.2329	0.2764	0.3260	0.3592
22	0.3608	0.4252	0.4975	0.5438	52	0.2307	0.2736	0.3228	0.3558
23	0.3528	0.4160	0.4862	0.5316	53	0.2284	0.2710	0.3198	0.3524
24	0.3443	0.4070	0.4757	0.5209	54	0.2262	0.2685	0.3168	0.3492
25	0.3369	0.3977	0.4662	0.5108	55	0.2242	0.2659	0.3139	0.3460
26	0.3306	0.3901	0.4571	0.5009	56	0.2221	0.2636	0.3111	0.3429
27	0.3242	0.3828	0.4487	0.4915	57	0.2201	0.2612	0.3083	0.3400
28	0.3180	0.3755	0.4401	0.4828	58	0.2181	0.2589	0.3057	0.3370
29	0.3118	0.3685	0.4325	0.4749	59	0.2162	0.2567	0.3030	0.3342
30	0.3063	0.3624	0.4251	0.4670	60	0.2144	0.2545	0.3005	0.3314

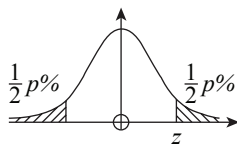
Percentage points of the χ^2 (chi-squared) distribution

$p\%$	99	97.5	95	90		10	5	2.5	1	0.5
$\nu = 1$.0001	.0010	.0039	.0158		2.706	3.841	5.024	6.635	7.879
2	.0201	.0506	0.103	0.211		4.605	5.991	7.378	9.210	10.60
3	0.115	0.216	0.352	0.584		6.251	7.815	9.348	11.34	12.84
4	0.297	0.484	0.711	1.064		7.779	9.488	11.14	13.28	14.86
5	0.554	0.831	1.145	1.610		9.236	11.07	12.83	15.09	16.75
6	0.872	1.237	1.635	2.204		10.64	12.59	14.45	16.81	18.55
7	1.239	1.690	2.167	2.833		12.02	14.07	16.01	18.48	20.28
8	1.646	2.180	2.733	3.490		13.36	15.51	17.53	20.09	21.95
9	2.088	2.700	3.325	4.168		14.68	16.92	19.02	21.67	23.59
10	2.558	3.247	3.940	4.865		15.99	18.31	20.48	23.21	25.19
11	3.053	3.816	4.575	5.578		17.28	19.68	21.92	24.72	26.76
12	3.571	4.404	5.226	6.304		18.55	21.03	23.34	26.22	28.30
13	4.107	5.009	5.892	7.042		19.81	22.36	24.74	27.69	29.82
14	4.660	5.629	6.571	7.790		21.06	23.68	26.12	29.14	31.32
15	5.229	6.262	7.261	8.547		22.31	25.00	27.49	30.58	32.80
16	5.812	6.908	7.962	9.312		23.54	26.30	28.85	32.00	34.27
17	6.408	7.564	8.672	10.09		24.77	27.59	30.19	33.41	35.72
18	7.015	8.231	9.390	10.86		25.99	28.87	31.53	34.81	37.16
19	7.633	8.907	10.12	11.65		27.20	30.14	32.85	36.19	38.58
20	8.260	9.591	10.85	12.44		28.41	31.41	34.17	37.57	40.00
21	8.897	10.28	11.59	13.24		29.62	32.67	35.48	38.93	41.40
22	9.542	10.98	12.34	14.04		30.81	33.92	36.78	40.29	42.80
23	10.20	11.69	13.09	14.85		32.01	35.17	38.08	41.64	44.18
24	10.86	12.40	13.85	15.66		33.20	36.42	39.36	42.98	45.56
25	11.52	13.12	14.61	16.47		34.38	37.65	40.65	44.31	46.93
26	12.20	13.84	15.38	17.29		35.56	38.89	41.92	45.64	48.29
27	12.88	14.57	16.15	18.11		36.74	40.11	43.19	46.96	49.64
28	13.56	15.31	16.93	18.94		37.92	41.34	44.46	48.28	50.99
29	14.26	16.05	17.71	19.77		39.09	42.56	45.72	49.59	52.34
30	14.95	16.79	18.49	20.60		40.26	43.77	46.98	50.89	53.67
35	18.51	20.57	22.47	24.80		46.06	49.80	53.20	57.34	60.27
40	22.16	24.43	26.51	29.05		51.81	55.76	59.34	63.69	66.77
50	29.71	32.36	34.76	37.69		63.17	67.50	71.42	76.15	79.49
100	70.06	74.22	77.93	82.36		118.5	124.3	129.6	135.8	140.2

Percentage points of the t distribution

$v \backslash p\%$	10	5	2	1	
1	6.314	12.71	31.82	63.66	
2	2.920	4.303	6.965	9.925	
3	2.353	3.182	4.541	5.841	
4	2.132	2.776	3.747	4.604	
5	2.015	2.571	3.365	4.032	
6	1.943	2.447	3.143	3.707	
7	1.895	2.365	2.998	3.499	
8	1.860	2.306	2.896	3.355	
9	1.833	2.262	2.821	3.250	
10	1.812	2.228	2.764	3.169	
11	1.796	2.201	2.718	3.106	
12	1.782	2.179	2.681	3.055	
13	1.771	2.160	2.650	3.012	
14	1.761	2.145	2.624	2.977	
15	1.753	2.131	2.602	2.947	
20	1.725	2.086	2.528	2.845	
30	1.697	2.042	2.457	2.750	
50	1.676	2.009	2.403	2.678	
100	1.660	1.984	2.364	2.626	
∞	1.645	1.960	2.326	2.576	= percentage points of the Normal distribution $N(0, 1)$

Percentage points of the Normal distribution



p	10	5	2	1
z	1.645	1.960	2.326	2.576

Critical values for the Wilcoxon Single Sample test

1-tail	5%	2½%	1%	½%	1-tail	5%	2½%	1%	½%
2-tail	10%	5%	2%	1%	2-tail	10%	5%	2%	1%
n					n				
2	–	–	–	–	26	110	98	84	75
3	–	–	–	–	27	119	107	92	83
4	–	–	–	–	28	130	116	101	91
5	0	–	–	–	29	140	126	110	100
6	2	0	–	–	30	151	137	120	109
7	3	2	0	–	31	163	147	130	118
8	5	3	1	0	32	175	159	140	128
9	8	5	3	1	33	187	170	151	138
10	10	8	5	3	34	200	182	162	148
11	13	10	7	5	35	213	195	173	159
12	17	13	9	7	36	227	208	185	171
13	21	17	12	9	37	241	221	198	182
14	25	21	15	12	38	256	235	211	194
15	30	25	19	15	39	271	249	224	207
16	35	29	23	19	40	286	264	238	220
17	41	34	27	23	41	302	279	252	233
18	47	40	32	27	42	319	294	266	247
19	53	46	37	32	43	336	310	281	261
20	60	52	43	37	44	353	327	296	276
21	67	58	49	42	45	371	343	312	291
22	75	65	55	48	46	389	361	328	307
23	83	73	62	54	47	407	378	345	322
24	91	81	69	61	48	426	396	362	339
25	100	89	76	68	49	446	415	379	355
					50	466	434	397	373

Summary of updates

Date	Version	Section	Title of section	Change
June 2018	1.1	Front cover	Disclaimer	Addition of Disclaimer
March 2019	1.2	Multiple		Correction of minor typographical errors
September 2019	1.3	Multiple		Correction of minor typographical errors







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